

ecCodes: Using BUFR Tools

Part 1

Computer User Training Course 2018

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- **BUFR Tools basics and getting help**
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ecCodes command line tools – basic concepts

- The ecCodes tools are a set of command line programs for interactive and batch processing of BUFR data
- They provide ready and tested solutions to the most common processing of BUFR data
- Their use will avoid the need to write new code and thus speed up your work
 - Consider using ecCodes tools instead of writing your own program
- The tools are provided with a common set of options so that it is quick to apply the same options to different tools
- Use of the tools is recommended whenever possible!

BUFR Tools – basics

All of the tools use a common syntax

```
bufr_<tool> [options] bufr_file [bufr_file] ... [output_bufr]
```

- Tool to count the messages in a BUFR file
 - `bufr_count`
- Tools to inspect the content of and compare BUFR files
 - `bufr_dump`, `bufr_ls`, `bufr_get`, `bufr_compare`
- Tool to copy some messages
 - `bufr_copy`
- Tools to change the content of a BUFR message
 - `bufr_filter`

Getting help

- **UNIX 'man'-style pages are available for each tool by running the tool without any options or input files**

```
> bufr_dump
```

```
NAME      bufr_dump
```

```
DESCRIPTION
```

```
    Dump the content of a BUFR file in different formats.
```

```
USAGE
```

```
bufr_dump [options] bufr_file bufr_file ...
```

```
OPTIONS
```

```
-j s/f/a  JSON mode (JavaScript Object Notation).
```

```
-p        Plain dump
```

```
...
```

Documentation

- The ecCodes home page is available at <https://software.ecmwf.int/wiki/display/ECC/ecCodes+Home>
- The BUFR Tools are documented at <https://software.ecmwf.int/wiki/display/ECC/BUFR+tools>
Includes some examples of how to use the tools
- The WMO FM 94 BUFR edition 3 and edition 4 Manuals can be obtained from <http://www.wmo.int/pages/prog/www/WMOCodes.html>
- The ecCodes software can be downloaded from <https://software.ecmwf.int/wiki/display/ECC/Releases>

codes_info – information about ecCodes installation

The **codes_info** tool gives basic information about the ecCodes package being used

- ecCodes Version
- Path to definition files: **ECCODES_DEFINITION_PATH**
- Path to sample files: **ECCODES_SAMPLES_PATH**

```
> codes_info
```

```
eccodes Version 2.6.0
```

```
Default definition files path is used: /usr/local/apps/eccodes/2.6.0/share/eccodes/definitions  
Definition files path can be changed setting ECCODES_DEFINITION_PATH environment variable
```

```
Default SAMPLES path is used: /usr/local/apps/eccodes/2.6.0/share/eccodes/samples  
SAMPLES path can be changed setting ECCODES_SAMPLES_PATH environment variable
```

bufr_count – count BUFR messages

- Counts (very quickly) the number of BUFR messages in a list of files
- Syntax

```
bufr_count [-v] bufr_file1 [bufr_file2 ...]
```

(takes wildcards)

Without the ‘-v’ option, it prints the total number of messages. With ‘-v’ (verbose) it prints the number of messages per file as well as the total

```
> bufr_count syn*.bufr
```

```
5
```

```
> bufr_count -v syn*.bufr
```

```
1 syno_3.bufr  
1 syno_4.bufr  
3 syno_multi.bufr  
5 total
```


bufr_dump – dump content of BUFR files

- Use **bufr_dump** to dump the content of a file containing one or more BUFR messages
- Various output formats are supported:
 - **Plain mode** prints 'key=value' pairs
 - **JSON mode** prints in JavaScript Object Notation
 - **Octet mode** provides a WMO documentation style dump (no unpacking)
- The default format (without any options) is the **JSON mode**
 - JSON is an open standard format that uses human-readable text to transmit data objects consisting of attribute-value pairs
 - Easy to visualise/navigate

bufr_dump – examples

The simplest format is the “Plain” mode (option “-p”): each key printed with its value:

```
> bufr_dump -p ahws_139.bufr
```

```
edition=3
masterTableNumber=0
bufrHeaderSubCentre=0
bufrHeaderCentre=98
updateSequenceNumber=0
dataCategory=12
...
localNumberOfObservations=492
satelliteID=4
observedData=1
compressedData=1
unexpandedDescriptors=312061
directionOfMotionOfMovingObservingPlatform={
    294, 294, 294, 294, 294, 294, 294, 294, 294, 294, ...}
#1#backscatter={
    -14.3, -13.06, -12.1, -11.59, -11.4, -11.46, -11.98, ...}
...
#2#backscatter={
    -13.41, -11.91, -10.74, -10.78, -10.75, -10.99, -12.01, -12.26 ... }
...
surfaceSoilMoisture=MISSING
```

bufr_dump – examples

Without any options you get the JSON output:

```
> bufr_dump ahws_139.bufr
```

```
{ "messages" : [[
  { "key" : "edition",
    "value" : 3 },
  { "key" : "masterTableNumber",
    "value" : 0 },
  ...
  [ { "key" : "beamIdentifier",
      "value" : 1,
      "units" : "CODE TABLE" },
    [{ "key" : "radarIncidenceAngle",
        "value" : [47.91, 48.63, 49.34, 50.01, 50.7, ...],
        "units" : "deg" },
      [{
        "key" : "antennaBeamAzimuth",
        "value" : [126.79, 125.16, 123.52, 121.96, ... ],
        "units" : "deg" }
      ],
    ]
  }
  ...
  [ { "key" : "beamIdentifier",
      "value" : 2,
      "units" : "CODE TABLE" },
    ...
  ]
  ...
]
```

bufr_dump – examples

With option “-ja” you get the JSON output plus key attributes:

```
> bufr_dump -ja ahws_139.bufr
```

```
...
{ "key" : "beamIdentifier",
  "value" : 1,
  "index" : 21,
  "code" : "008085",
  "units" : "CODE TABLE",
  "scale" : 0,
  "reference" : 0,
  "width" : 3},
[ { "key" : "radarIncidenceAngle",
    "value" : [ ... ],
    "index" : 22,
    "code" : "002111",
    "units" : "deg",
    "scale" : 2,
    "reference" : 0,
    "width" : 13
  },
...

```

bufr_dump – examples

With option “-jf” you get the FLAT JSON output plus key attributes:

```
> bufr_dump -jf ahws_139.bufr
```

```
{ "key" : "centre",  
  "value" : 99,  
  "index" : 1,  
  "code" : "001033",  
  "units" : "CODE TABLE",  
  "scale" : 0,  
  "reference" : 0,  
  "width" : 8 },  
...  
{ "key" : "beamIdentifier",  
  "value" : 1,  
  "index" : 21,  
  "code" : "008085",  
  "units" : "CODE TABLE",  
  "scale" : 0,  
  "reference" : 0,  
  "width" : 3 },  
{  
  "key" : "radarIncidenceAngle",  
  "value" : [63.96, 63.5, 63.04, ...]  
  ...  
}  
...
```

bufr_dump – missing values

bufr_dump with JSON shows MISSING values as “null”:

```
> bufr_dump -jf ahws_139.bufr
```

```
{  
  "key" : "surfaceSoilMoisture",  
  "value" : null,  
  "index" : 65,  
  "code" : "040001",  
  "units" : "%",  
  "scale" : 1,  
  "reference" : 0,  
  "width" : 10 },  
...  
{  
  "key" : "backscatter",  
  "value" : null,  
  "index" : 72,  
  "code" : "021062",  
  "units" : "dB",  
  "scale" : 2,  
  "reference" : -5000,  
  "width" : 13 },  
...
```

bufr_dump – examples

Octet mode: WMO documentation style (low-level, no unpacking the data section):

```
> bufr_dump -O ahws_139.bufr
```

```
***** FILE: ahws_139.bufr
#===== MESSAGE 1 ( length=13854 ) =====
1-4      identifier = BUFR
5-7      totalLength = 13854
8        edition = 3
===== SECTION_1 ( length=18, padding=0 ) =====
1-3      section1Length = 18
4        masterTableNumber = 0
5        bufrHeaderSubCentre = 0 [Absent (common/c-1.table) ]
6        bufrHeaderCentre = 98 [European Centre for Medium-Range Weather Forecasts (common/c-1.table) ]
7        updateSequenceNumber = 0
8        section1Flags = 128 [10000000]
9        dataCategory = 12
10       dataSubCategory = 139
11       masterTablesVersionNumber = 13
12       localTablesVersionNumber = 1
13       typicalYearOfCentury = 12
14       typicalMonth = 11
15       typicalDay = 2
...
===== SECTION_2 ( length=52, padding=0 ) =====
1-3      section2Length = 52
4        reservedSection2 = 0
5        rdbType = 12
18       ...
```

bufr_dump (online) – BUFR Validator

- You can also view the JSON output with additional functionality via the **BUFR validator** web page: <http://apps.ecmwf.int/codes/bufr/validator/>
- The array sizes are shown
- Tooltips display the key attributes as well as array entries
- Here the **MISSING** value is shown as “missing”

Note:

- Only the first message is displayed
- There is a 2MB size limit

beamIdentifier: 1	
beamIdentifier:	1
radarIncidenceAngle:	[63.96, 63.5, ..., 62.79, 63.23] (492 Items) deg
antennaBeamAzimuth:	[126.79, 125.16, ..., 150.77, 150.67] (492 Items) deg
backscatter:	[-14.3, -13.06, ..., -15.22, -15.53] (492 Items) dB
radiometricResolutionNoiseValue:	[7.4, 5.3, ..., 11.5, 11.8] (492 Items) %
ascatKpEstimateQuality:	0
ascatSigma0Usability:	0
ascatUseOfSyntheticData:	0
ascatSyntheticDataQuantity:	0
ascatSatelliteOrbitAndAttitudeQuality:	0
ascatSolarArrayReflectionContamination:	0
ascatTelemetryPresenceAndQuality:	0
ascatExtrapolatedReferenceFunctionPresence:	0
landFraction:	1

▶ beamIdentifier: 2

▶ beamIdentifier: 3

Practical

- Copy the BUFR data files to your \$SCRATCH

```
cd $SCRATCH
cp -r ~trx/ecCodes/2018/BufrFiles ./
cd BufrFiles
```

- Experiment with the bufr_dump tool. Store the output JSON file e.g.
bufr_dump ahws_139.bufr > ahws_139.json
- View the generated JSON files (e.g. with the editor “kate” which understands JSON and can expand/collapse the nodes)
- Try JSON options “-ja”, “-jf” and also the plain format “-p”
- Look out for keys with MISSING values
- View the dump on <http://apps.ecmwf.int/codes/bufr/validator/>

bufr_ls – list the content of BUFR files

- Use **bufr_ls** to list the high-level content (**header**) of BUFR files
- Without options **bufr_ls** prints a default list of keys
 - The default list printed can vary depending on the type of BUFR
- Options exist to specify the set of header keys to print
- **bufr_ls** does not fail if a key is not found
- Not suitable for viewing array information (data section). Later on we will cover a more powerful tool for this purpose (**bufr_filter**)

bufr_ls – usage

```
bufr_ls [options] bufr_file bufr_file ...
```

Options

`-p key[:{s|i|d}],...` **Keys to print**
`-w key[:{s|i|d}]{=|!=}value,...` **Where clause**
...

bufr_ls – examples

Use **-p** option to specify a list of header keys to be printed:

```
> bufr_ls tropical_cyclone.bufr
```

```
tropical_cyclone.bufr
```

centre	masterTablesVersionNumber	localTablesVersionNumber	...	numberOfSubsets	satelliteID
98	16	0	...	52	0
98	16	0	...	52	0
98	16	0	...	37	0

```
3 of 3 messages in tropical_cyclone.bufr
```

```
> bufr_ls -p centre:s,numberOfSubsets,satelliteID tropical_cyclone.bufr
```

```
tropical_cyclone.bufr
```

centre	numberOfSubsets	satelliteID
ecmf	52	0
ecmf	52	0
ecmf	37	0

```
3 of 3 messages in tropical_cyclone.bufr
```

bufr_ls – examples

- When a header key is not present in the BUFR file, it returns “not found” for this key

```
> bufr_ls -p my_key file.bufr
```

```
file.bufr
```

```
my_key
```

```
not found
```

```
> echo $?
```

```
0
```

exit code returned = 0



bufr_ls – using the ‘where’ option

- The ‘where option’ **-w** can be used with several other BUFR tools
- Constraints are of the form **key=value** or **key!=value**

`-w key[:{s|i|d}]=value, key[:{s|i|d}]!=value`

- Messages are processed only if they match ALL key/value constraints
- Values separated by ‘/’ (forward slash) represent “OR” condition

```
> bufr_ls -w numberOfSubsets=52 file.bufr
...
> bufr_ls -w typicalDate!=20090124,centre=80/98 file.bufr
...
> bufr_ls -w count=3 file.bufr
```

bufr_get – get key / value pairs

- Use `bufr_get` to get the values of one or more header keys from one or more BUFR files – very similar to `bufr_ls`
- By default `bufr_get` **fails** if an error occurs (e.g. key not found) returning a non-zero exit code
 - Suitable for use in scripts to obtain key values from messages
 - Can force `bufr_get` not to fail on error
- Format of floating point values can be controlled with a C-style format statement