

Post-Processing of Ensemble Forecasts

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Outline

- Motivation
- Methods
- Training data sets
- Results

This lecture is focussed on application to medium-range forecasts, but the theory and methods are general.

Motivation

- Raw ENS forecasts are subject to forecast bias and dispersion errors, i.e. uncalibrated
- The goal of calibration is to correct for such known model deficiencies, i.e. to construct predictions with statistical properties similar to the observations
- A number of statistical methods exist for post-processing ensembles
- Calibration needs a record of prediction-observation pairs
- Calibration is particularly successful at station locations with long historical data record (-> downscaling)

Calibration methods

- Bias correction
- Multiple implementation of deterministic MOS
- Ensemble dressing
- Bayesian model averaging
- Non-homogenous Gaussian regression
- Logistic regression
- Analogue method



Bias correction

- As a simple first order calibration a bias correction can be applied:

$$c = -\frac{1}{N} \sum_{i=1}^N \bar{e}_i + \frac{1}{N} \sum_{i=1}^N o_i$$

with: \bar{e}_i = ensemble mean of the i^{th} forecast

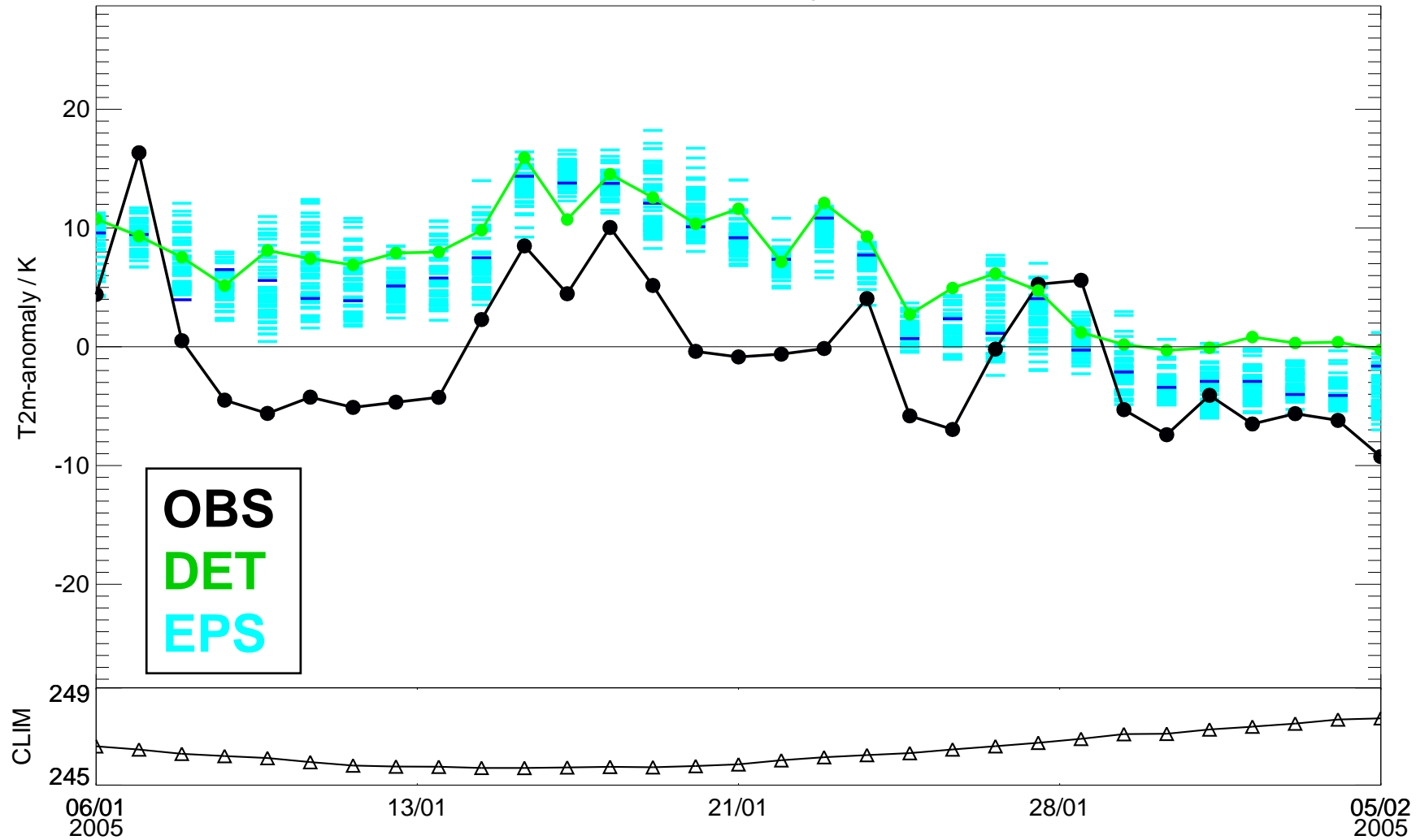
o_i = value of i^{th} observation

N = number of observation-forecast pairs

- This correction is added to each ensemble member, i.e. spread is not affected
- Particularly useful/successful at locations with features not resolved by model and causing significant bias

Bias correction

Station: ULAN-UDE (# 30823, Height: 515m) Lead: 120h

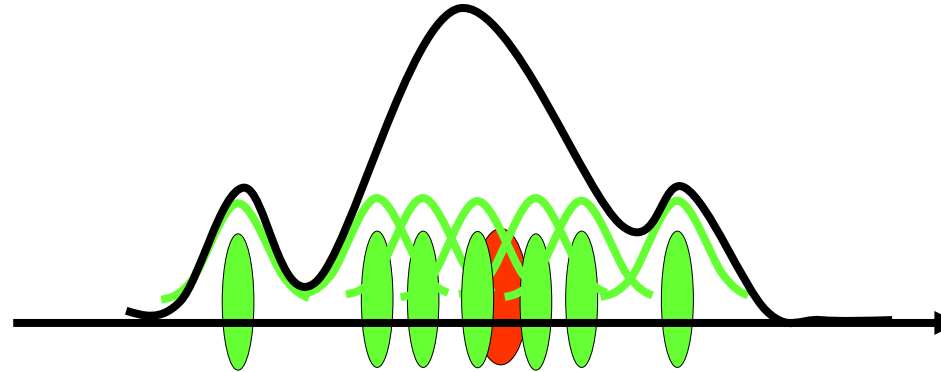


Multiple implementation of deterministic MOS

- A possible approach for calibrating ensemble predictions is to simply correct each individual ensemble member according to its deterministic model output statistic (MOS)
- **BUT:** this approach is conceptually inappropriate since for longer lead-times the MOS tends to correct towards climatology
 - all ensemble members tend towards climatology with longer lead-times
 - decreased spread with longer lead-times
 - in contradiction to increasing uncertainty with increasing lead-times
- (Discontinued) experimental product at <http://www.nws.noaa.gov/mdl/synop/enstxt.php>

Ensemble dressing

- Define a probability distribution around each ensemble member (“dressing”)



- A number of methods exist to find appropriate dressing kernel (“best-member” dressing, “error” dressing, “second moment constraint” dressing, etc.)
- Average the resulting n_{ens} distributions to obtain final pdf



Ensemble Dressing

- (Gaussian) ensemble dressing calculates the forecast probability for the quantiles q as:

$$P(v \leq q) = \frac{1}{n_{ens}} \sum_{i=1}^{n_{ens}} \Phi \left[\frac{q - \tilde{x}_i}{\sigma_D} \right]$$

with: Φ = CDF of standard Gaussian distribution
 \tilde{x}_i = **bias-corrected** ensemble-member

- Key parameter is the standard deviation of the Gaussian dressing kernel
- Simple approach: “best member” dressing, take standard deviation from r.m.s. difference of (obs-best member) from training set.



Ensemble Dressing

- Common approach: second-moment constraint dressing

$$\sigma_D^2 = \sigma_{\bar{x}-y}^2 - \left(1 + \frac{1}{n_{ens}}\right) \bar{\sigma}_{ens}^2$$

error variance of the ensemble-mean FC

average of the ensemble variances over the training data

- BUT: this can give negative or unstable variances, if model is already near to or over-dispersive.
- Ensemble dressing to generate a pdf is only suitable for *under-dispersive* forecasts.



Bayesian Model Averaging

- BMA closely linked to ensemble dressing
- Differences:
 - dressing kernels do not need to be the same for all ensemble members
 - different estimation method for kernels
- Useful for giving different ensemble members (models) different weights:

$$P(v \leq q) = w_1 \Phi \left[\frac{q - \tilde{x}_1}{\sigma_1} \right] + w_e \sum_{j=2}^{n_{ens}} \Phi \left[\frac{q - \tilde{x}_j}{\sigma_e} \right]$$

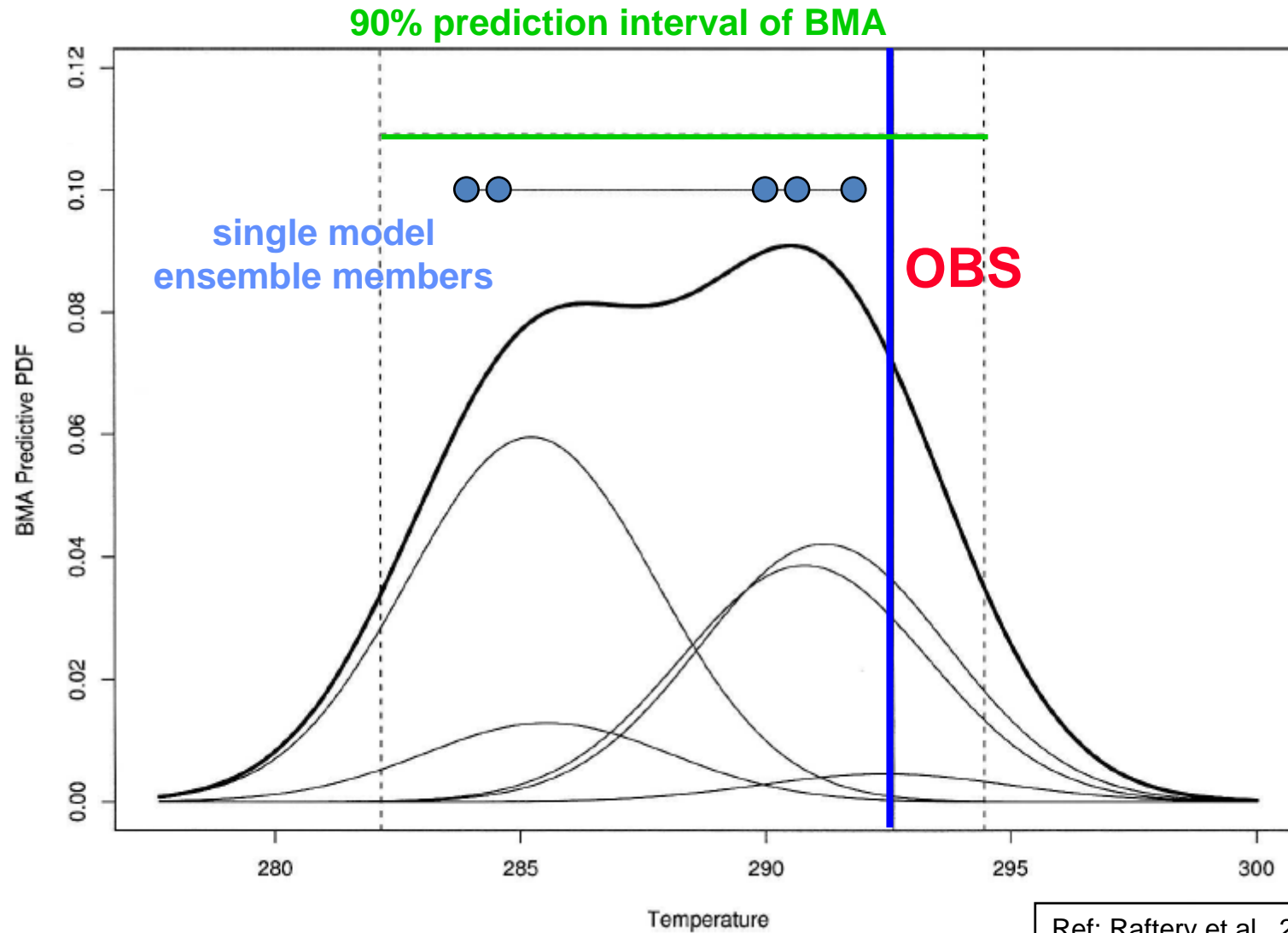
with: $w_1 + w_e (n_{ens} - 1) = 1$

- Estimation of weights and kernels simultaneously via maximum likelihood, i.e. maximizing the log-likelihood function:

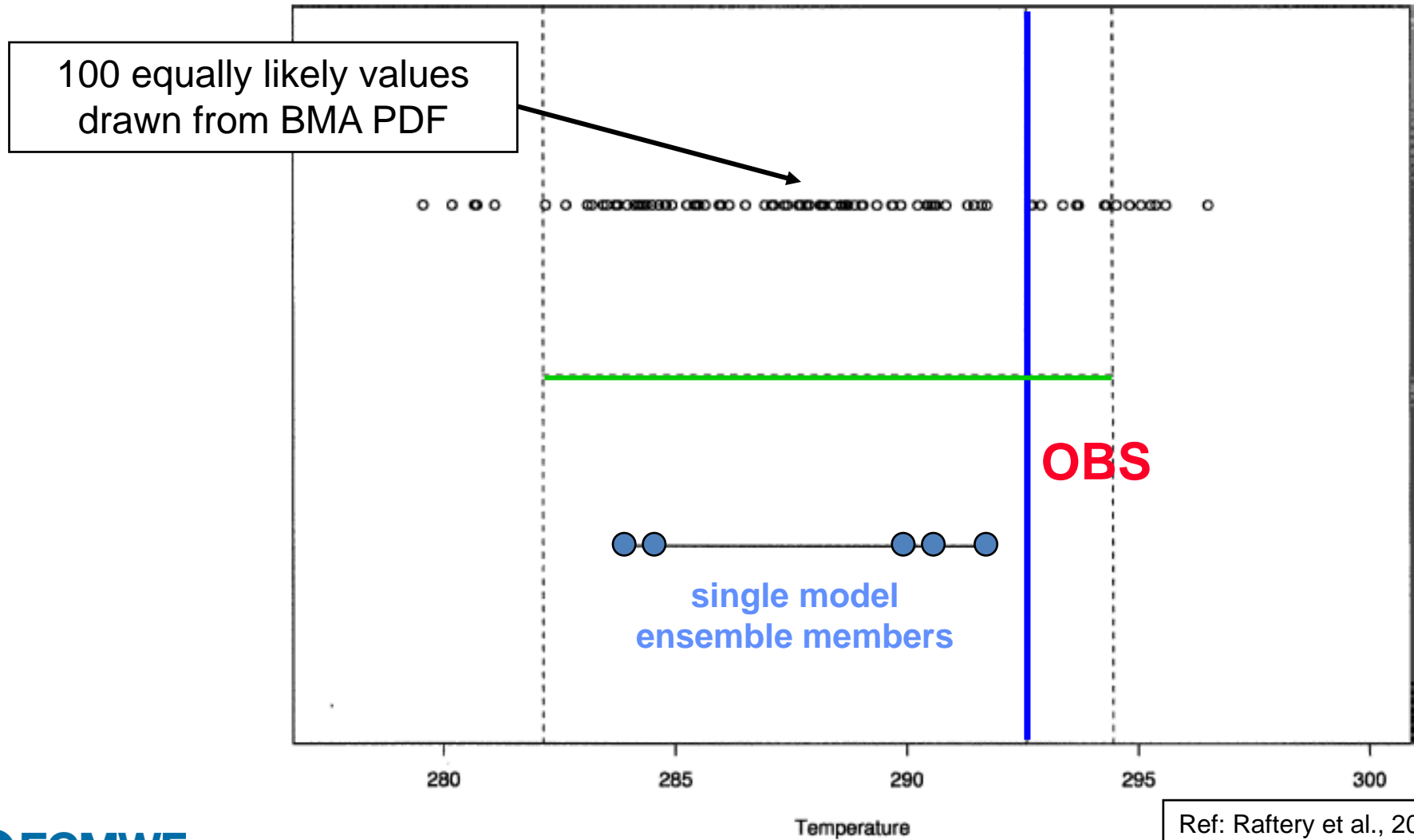
$$\ln(\Lambda) = - \sum_{i=1}^N \ln \left[w_1 g_1(v_i | \tilde{x}_{1,i}, \sigma_1^2) + w_e \sum_{j=2}^{n_{ens}} g_e(v_i | \tilde{x}_{j,i}, \sigma_e^2) \right]$$

$g_1, g_e = \text{Gaussian PDF's}$

BMA: example



BMA: recovered ensemble members





Non-homogenous Gaussian Regression

- In order to account for existing spread-skill relationships we model the variance of the error term as a function of the ensemble spread s_{ens} :

$$P(v \leq q) = \Phi \left[\frac{q - (a + b\bar{x}_{ens})}{\sqrt{c + ds_{ens}^2}} \right]$$

- The parameters a, b, c, d are fit iteratively by minimizing the CRPS of the training data set
- Interpretation of parameters:
 - bias & general performance of ens-mean are reflected in a and b
 - large spread-skill relationship: $c \approx 0.0, d \approx 1.0$
 - small spread-skill relationship: $d \approx 0.0$
- Calibration provides mean and spread of Gaussian distribution
(called non-homogenous since variances of regression errors not the same for all values of the predictor, i.e. non-homogenous)



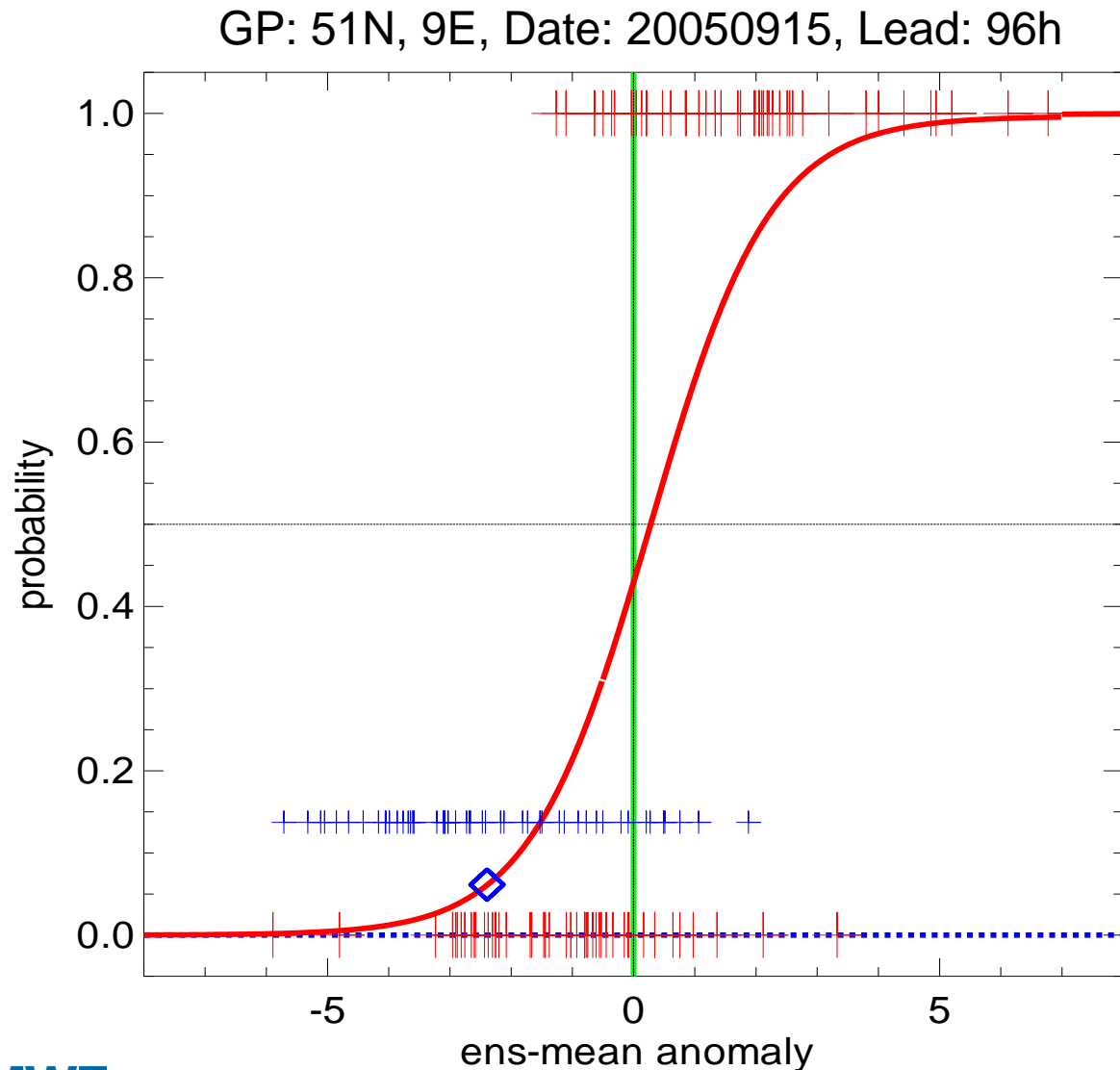
Logistic regression

- Logistic regression is a statistical regression model for Bernoulli-distributed dependent variables

$$P(v \leq q) = \frac{\exp(\beta_0 + \beta_1 \bar{x}_{ens})}{1 + \exp(\beta_0 + \beta_1 \bar{x}_{ens})}$$

- P is bound by 0,1 and produces an s-shaped prediction curve
 - steepness of curve (β_1) increases with decreasing spread, leading to sharper forecasts (more frequent use of extreme probabilities)
 - parameter β_0 corrects for bias, i.e. shifts the s-shaped curve

How does logistic regression work?



+ training data
100 cases (EnsMean)
(height = obs yes/no)

+ test data
(51 members)
(height = raw prob)

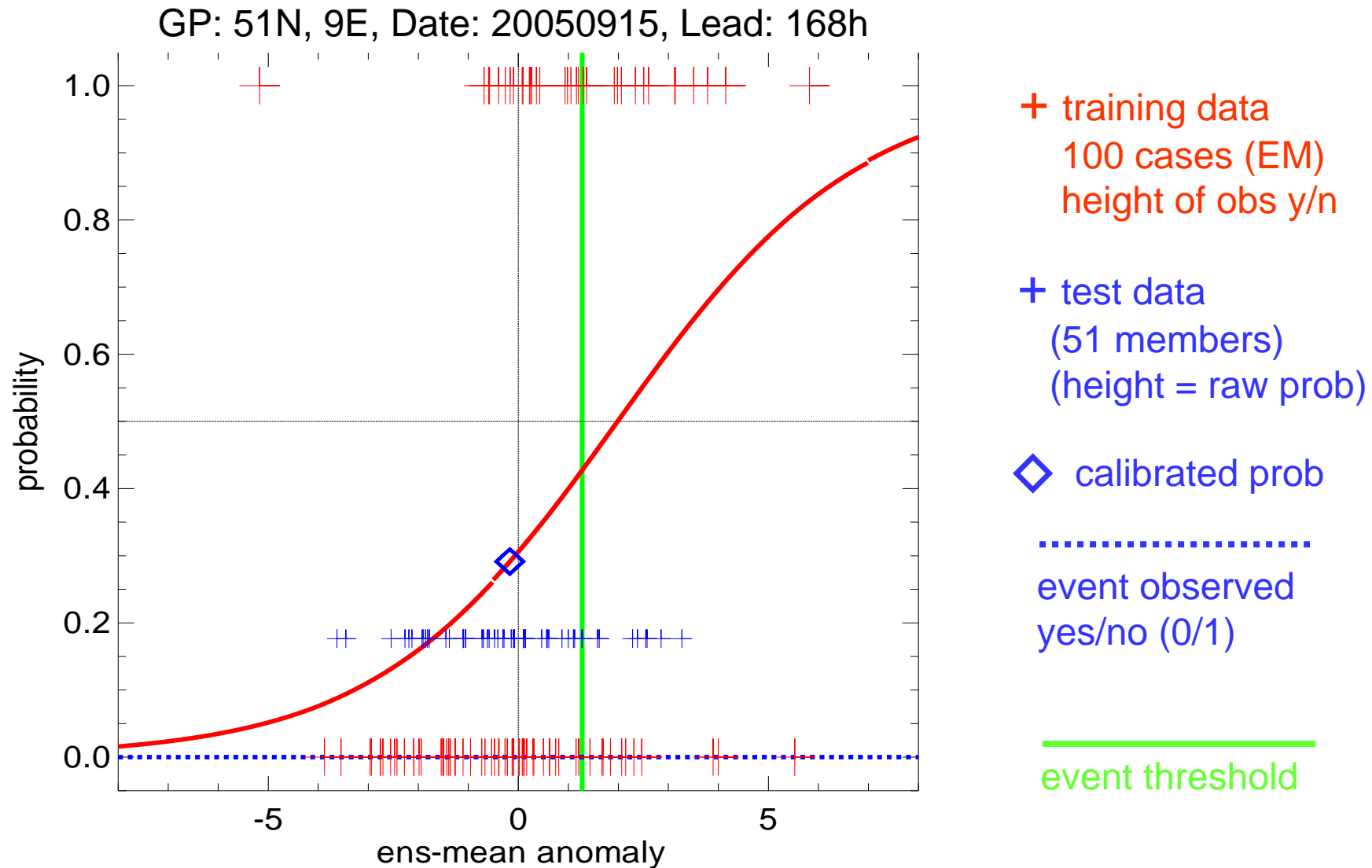
◇ calibrated prob

.....
event observed
yes/no (0/1)

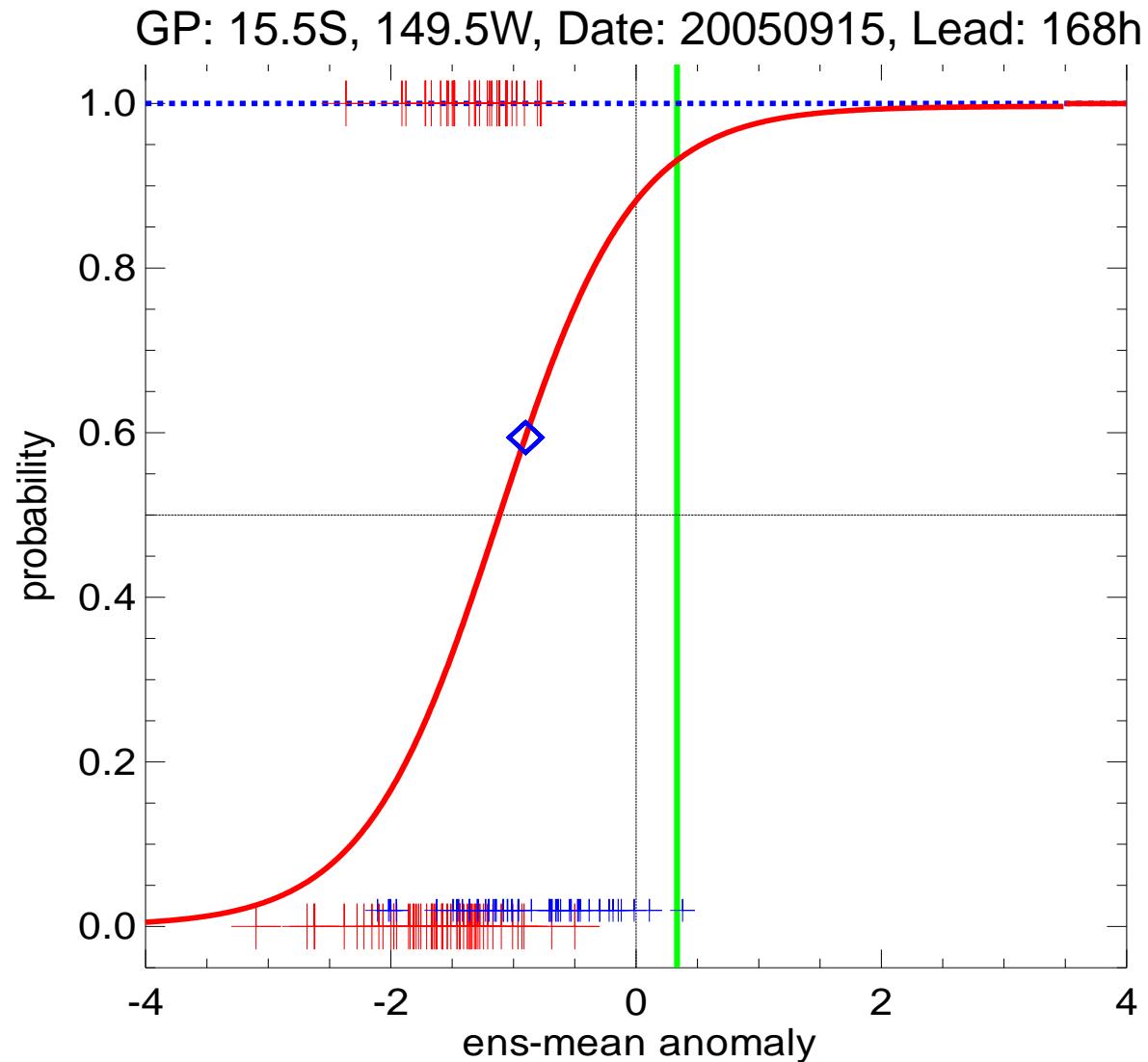
—————
event threshold

Event did
not happen
in this case

Example: LR-Probability worse!



Example: LR-Probability (much) better!



+ training data
100 cases (EM)
(height = obs y/n)

+ test data
(51 members)
(height = raw prob)

◇ calibrated prob

.....
event observed
yes/no (0/1)

—————
event threshold

Analogue method

- Full analogue theory assumes a nearly infinite training sample
- Justified under simplifying assumptions:
 - Search only for local analogues
 - Match the ensemble-mean fields
 - Consider only one model forecast variable in selecting analogues
- General procedure:
 - Take the ensemble mean of the forecast to be calibrated and find the n_{ens} closest forecasts to this in the training dataset
 - Take the corresponding observations to these n_{ens} re-forecasts and form a new calibrated ensemble
 - Construct probability forecasts from this analogue ensemble

Analogue method

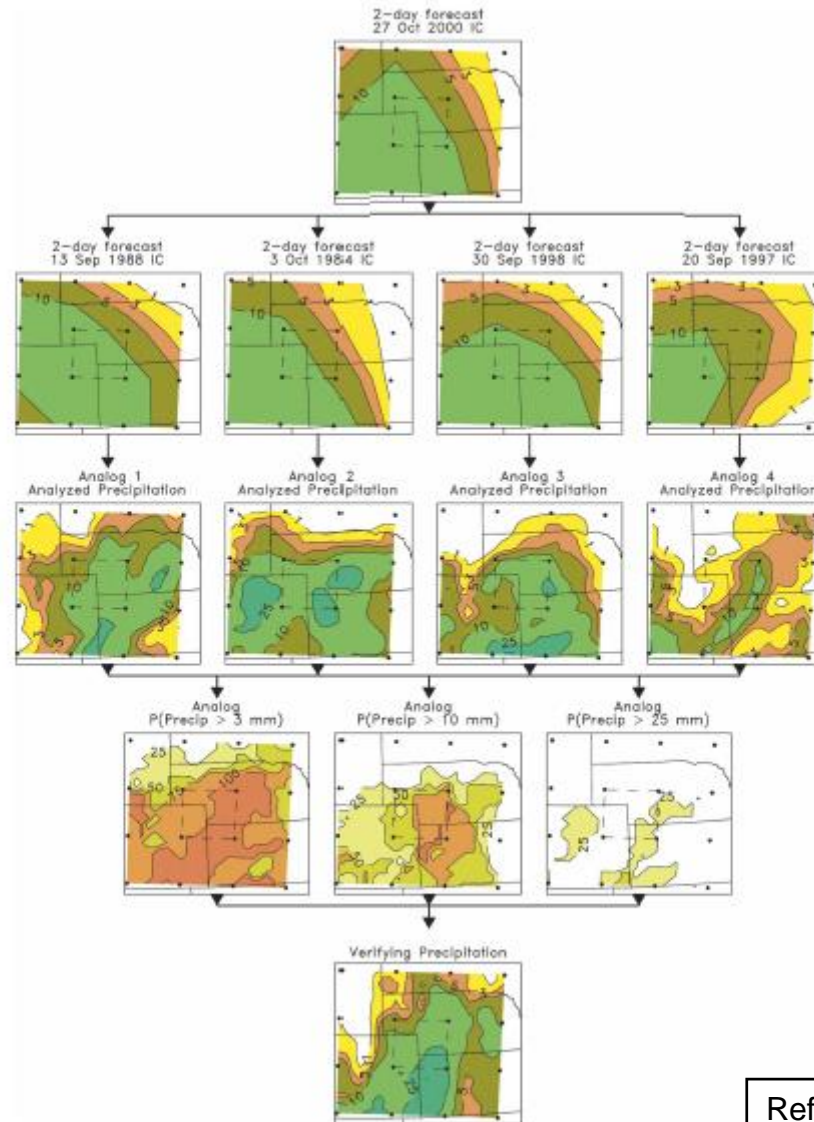
Forecast to be calibrated

Closest re-forecasts

Corresponding obs

Probabilities of analog-ens

Verifying observation



Training datasets

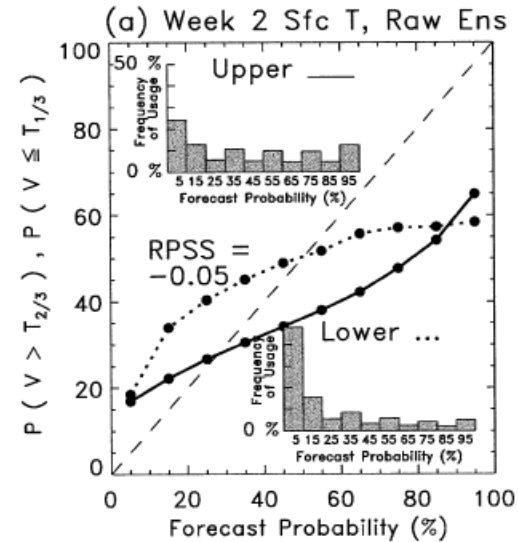
- All calibration methods need a training dataset, containing a number of forecast-observation pairs from the past
 - The more training cases the better
 - The model version used to produce the training dataset should be as close as possible to the operational model version
- For research applications often only one dataset is used to develop and test the calibration method. In this case cross-validation has to be applied.
- For operational applications one can use:
 - Operational available forecasts from e.g. past 30-40 days
 - Data from a re-forecast dataset covering a larger number of past forecast dates / years

“Perfect” Reforecast Data Set

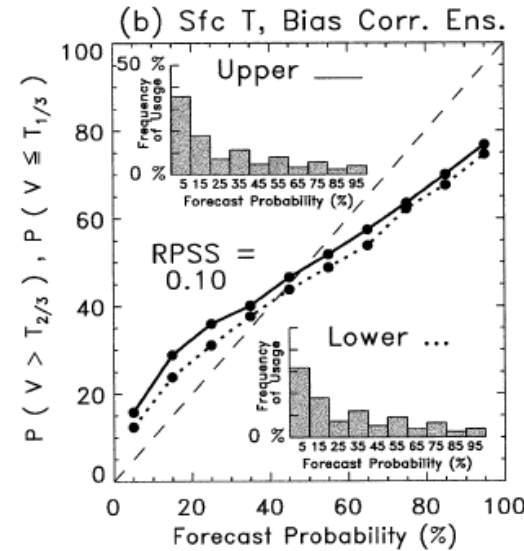
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Early motivating results from Hamill et al., 2004

Raw ensemble

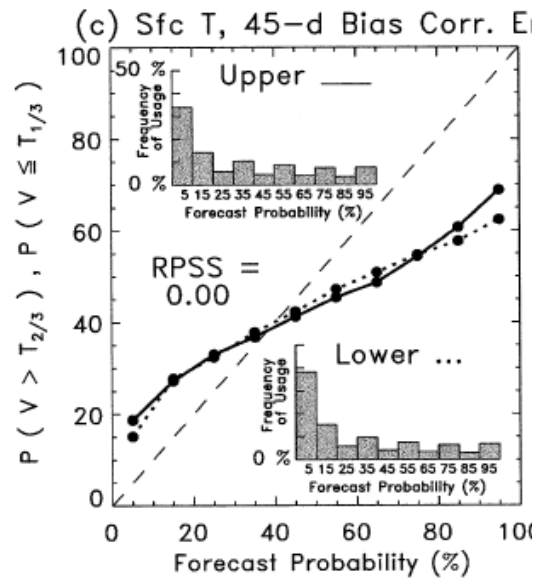


Bias corrected with refc data

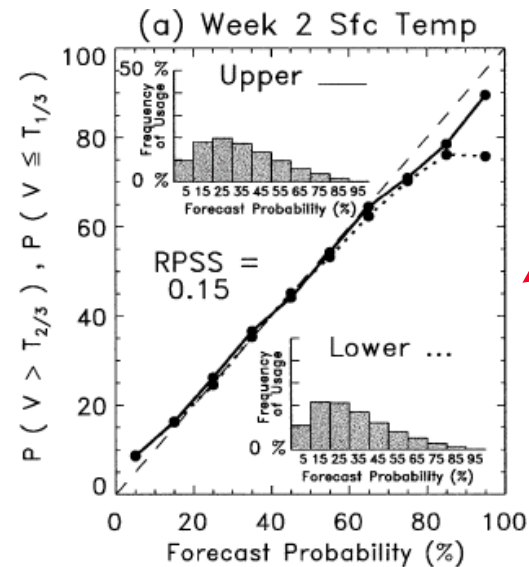


Achieved with "perfect" reforecast system!

Bias corrected with 45-d data



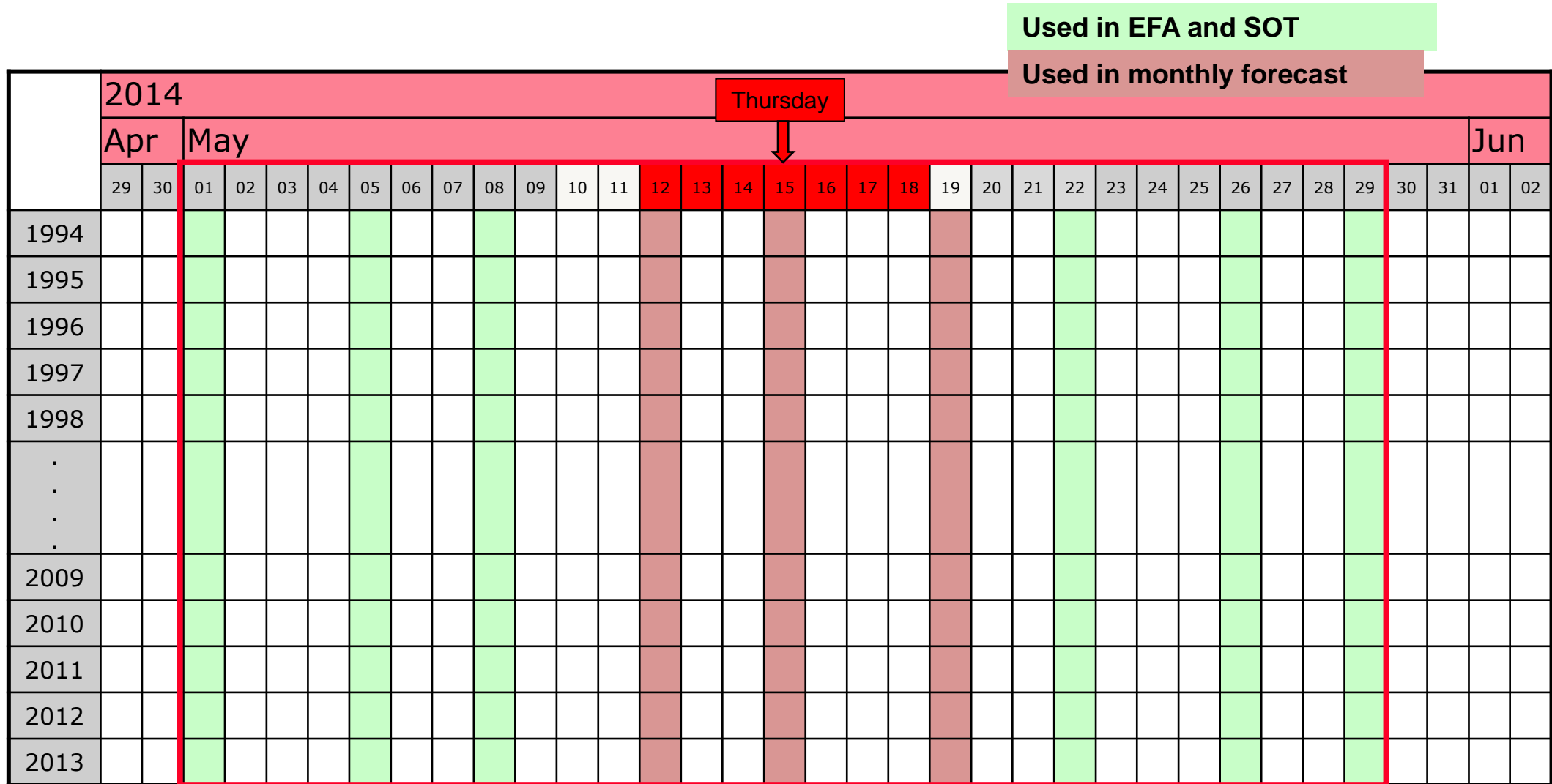
LR-calibrated ensemble



The 45-day unified ENS ensemble system

- Unified ENS ensemble system enables the production of a unified reforecast data set, to be used by:
 - EFI model climate
 - 15 day ENS calibration
 - Monthly forecasts anomalies and verification
- Efficient use of resources (computational and operational)
- “Realistic” reforecast system has to be an optimal compromise between affordability and needs of all three applications
- Use 11 member ensemble, twice per week, for last 20 years

Unified ENS Reforecasts



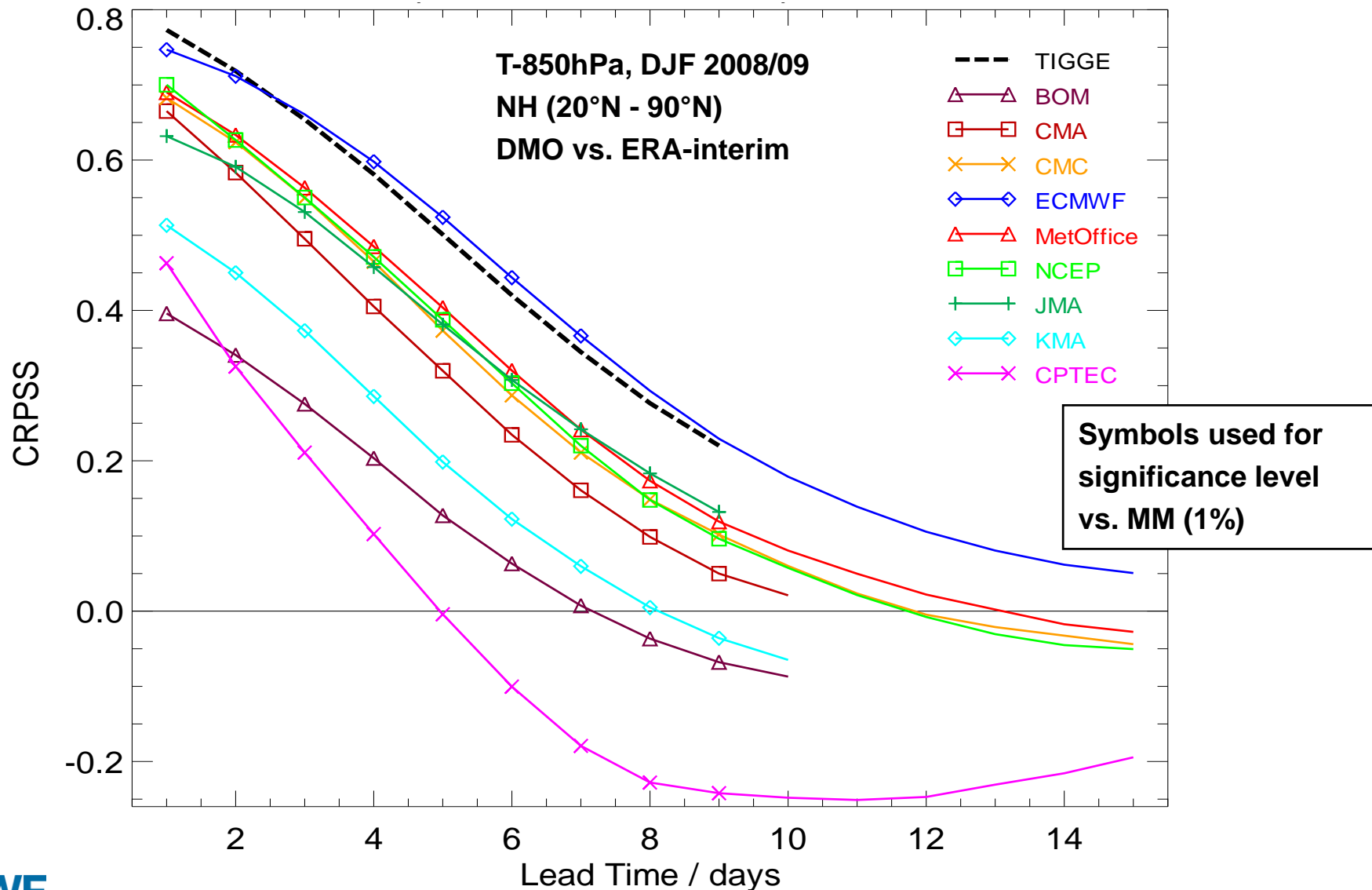
Testing the benefits of reforecast calibration

(Reference: Hagedorn et al, 2012)

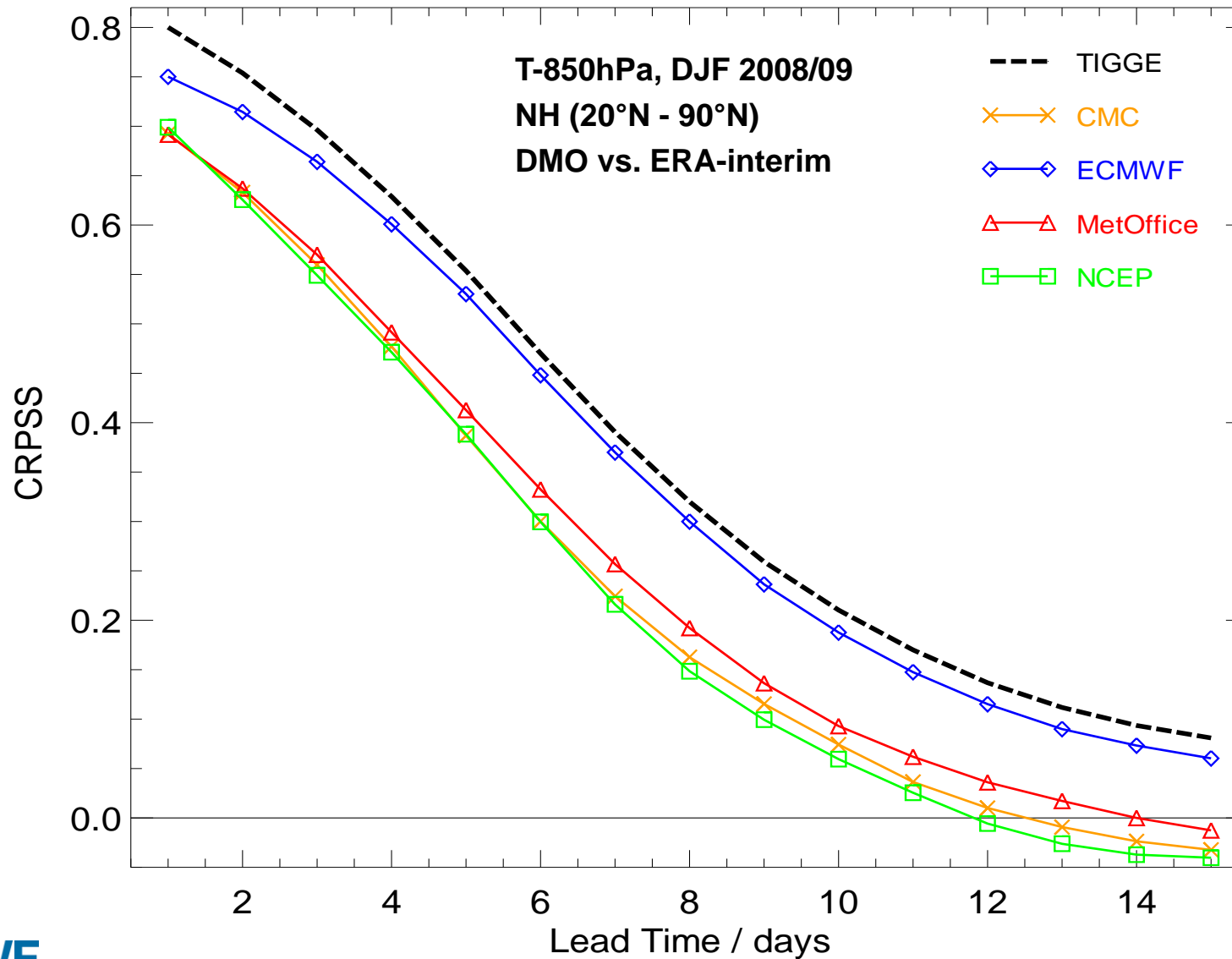
- One goal of the TIGGE project is to investigate whether multi-model predictions are an improvement to single model forecasts
- The goal of using reforecasts to calibrate single model forecasts is to provide improved predictions
- Questions:
 - What are the relative benefits (costs) of both approaches?
 - What is the mechanism behind the improvements?
 - Which is the “better” approach?

* TIGGE stands for: THORPEX Interactive Grand Global Ensemble

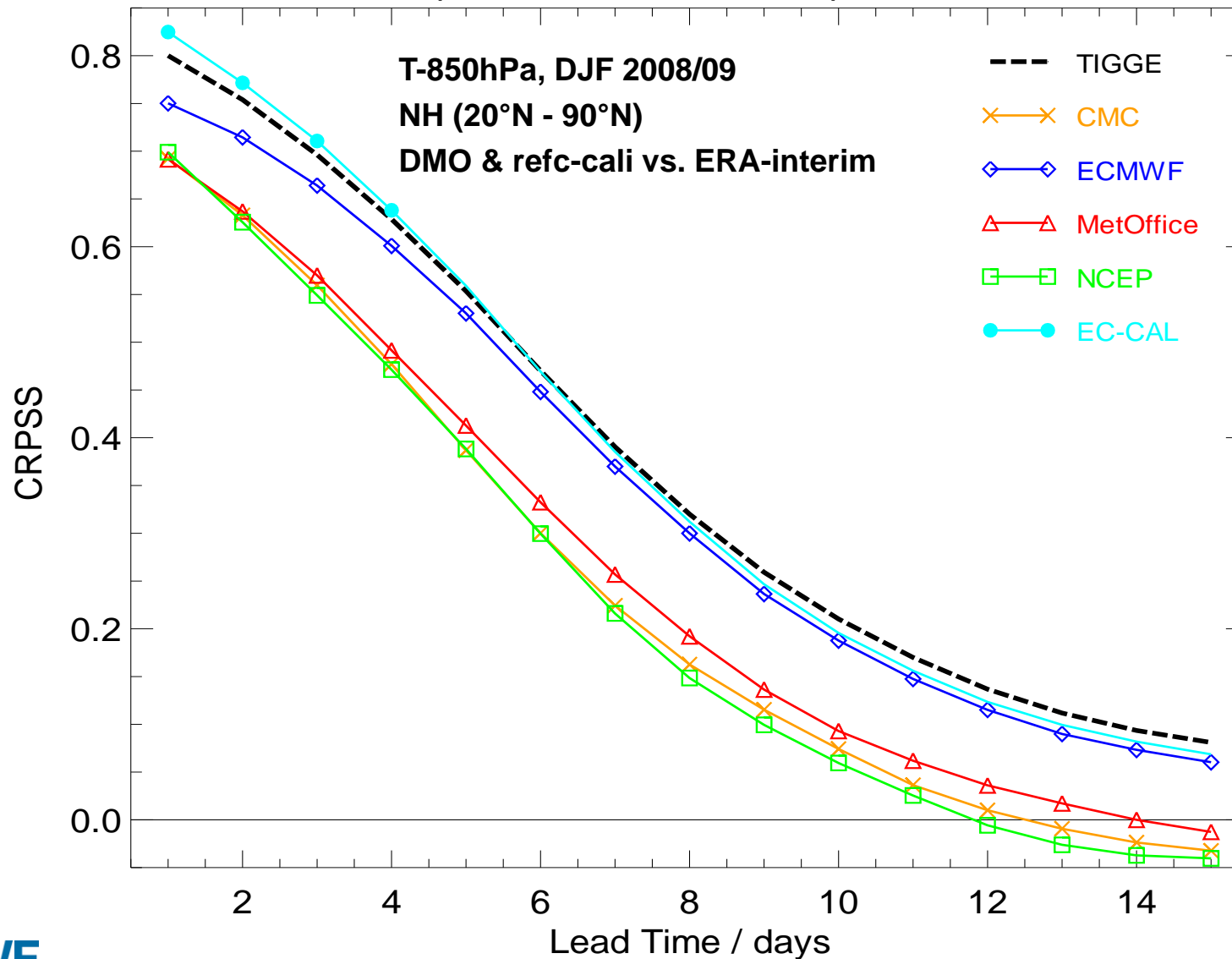
Comparing 9 TIGGE models & the MM



Comparing 4 TIGGE models & the MM

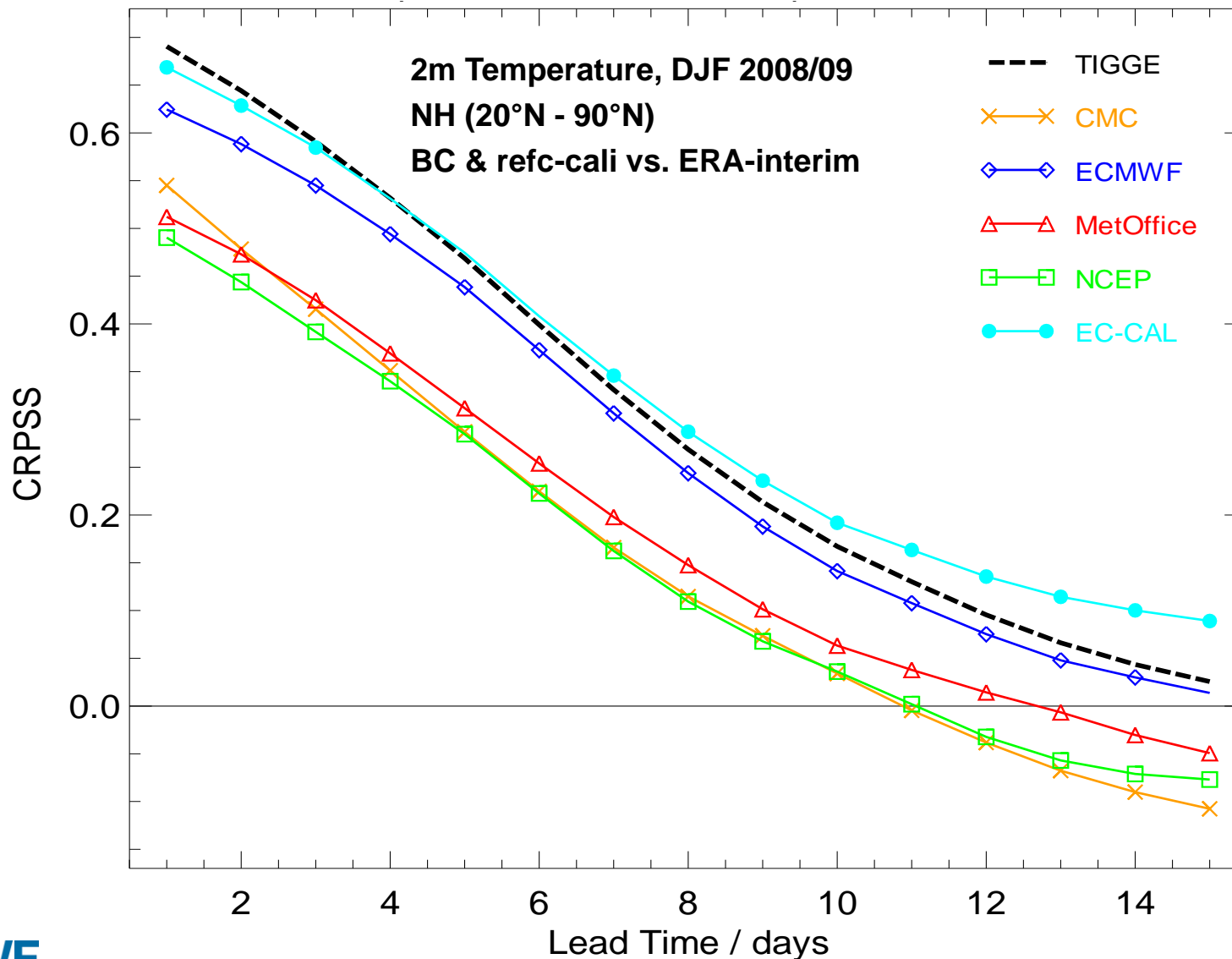


Comparing 4 TIGGE models, MM, EC-CAL

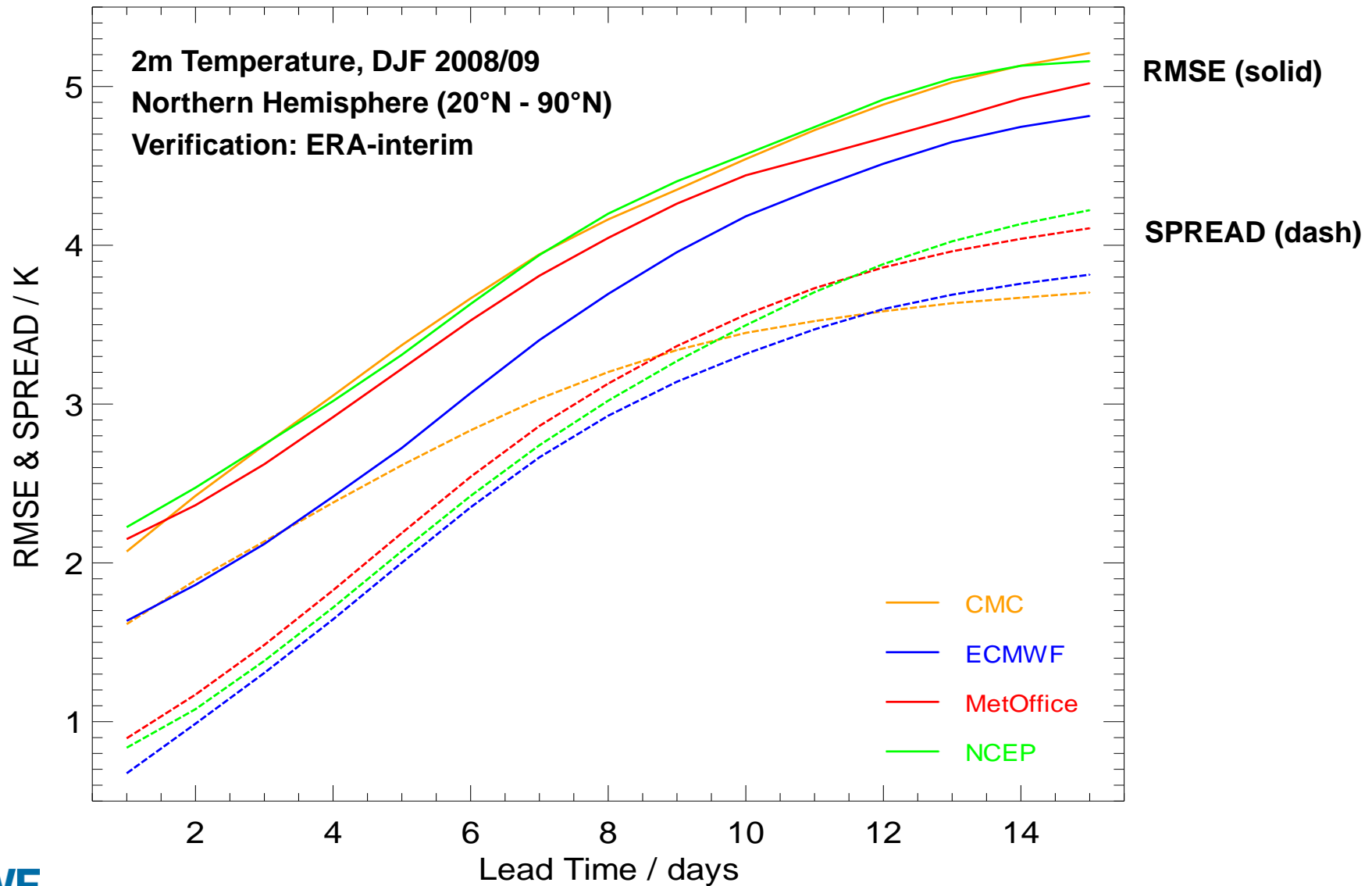


Note: *only* ECMWF is calibrated; other models do not have re-forecast datasets

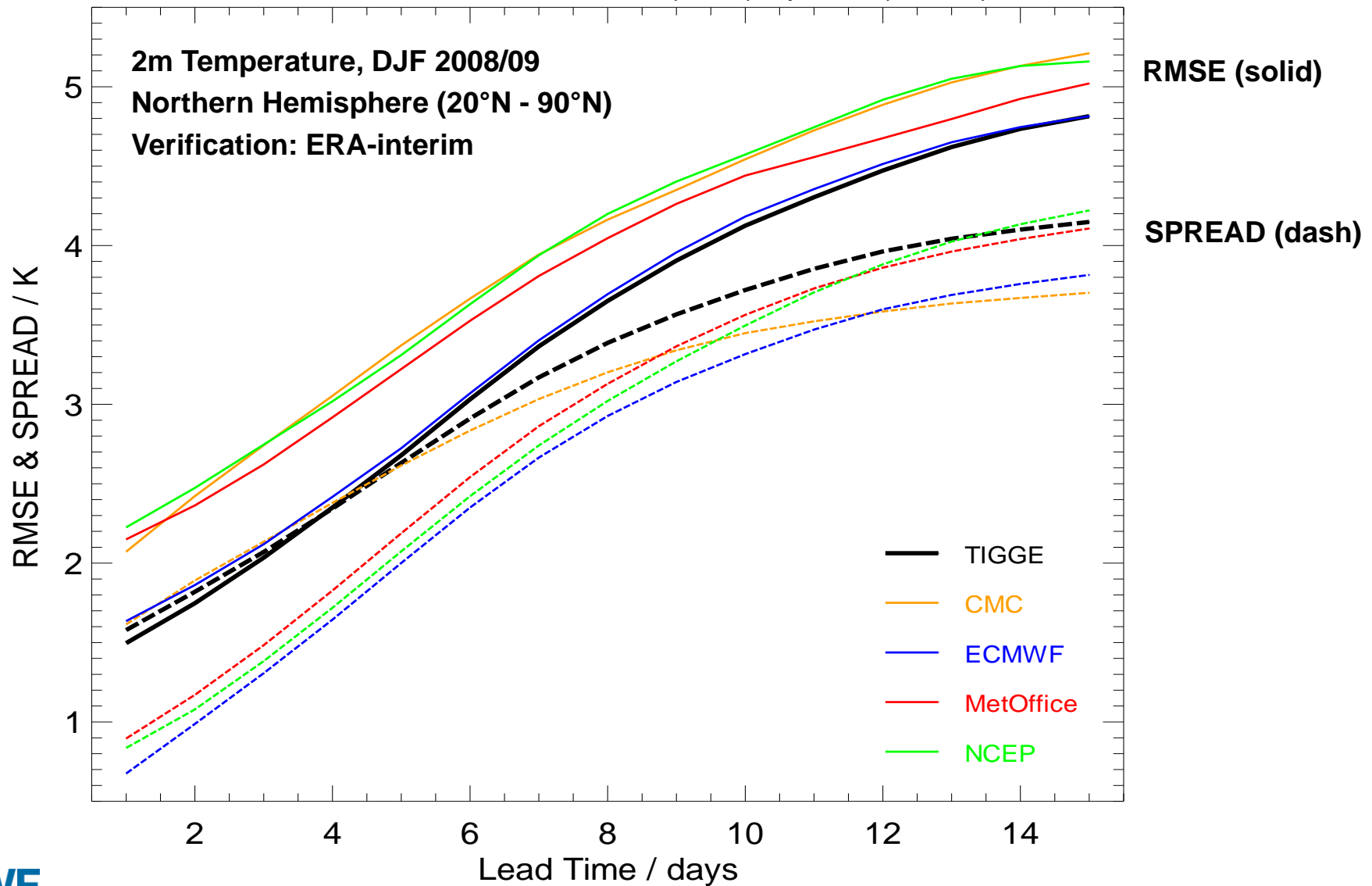
Comparing 4 TIGGE models, MM, EC-CAL



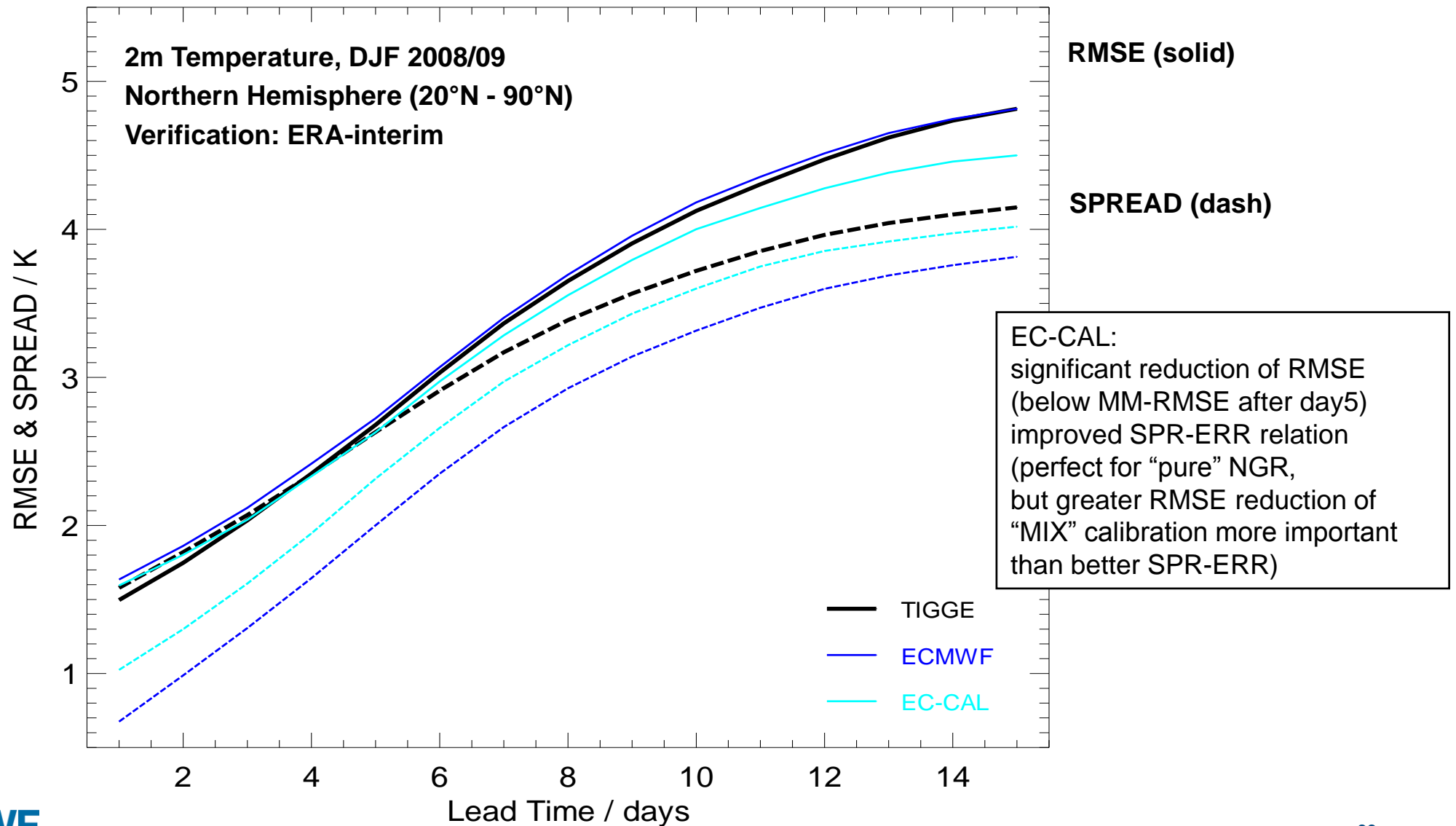
Mechanism behind improvements



Mechanism behind improvements

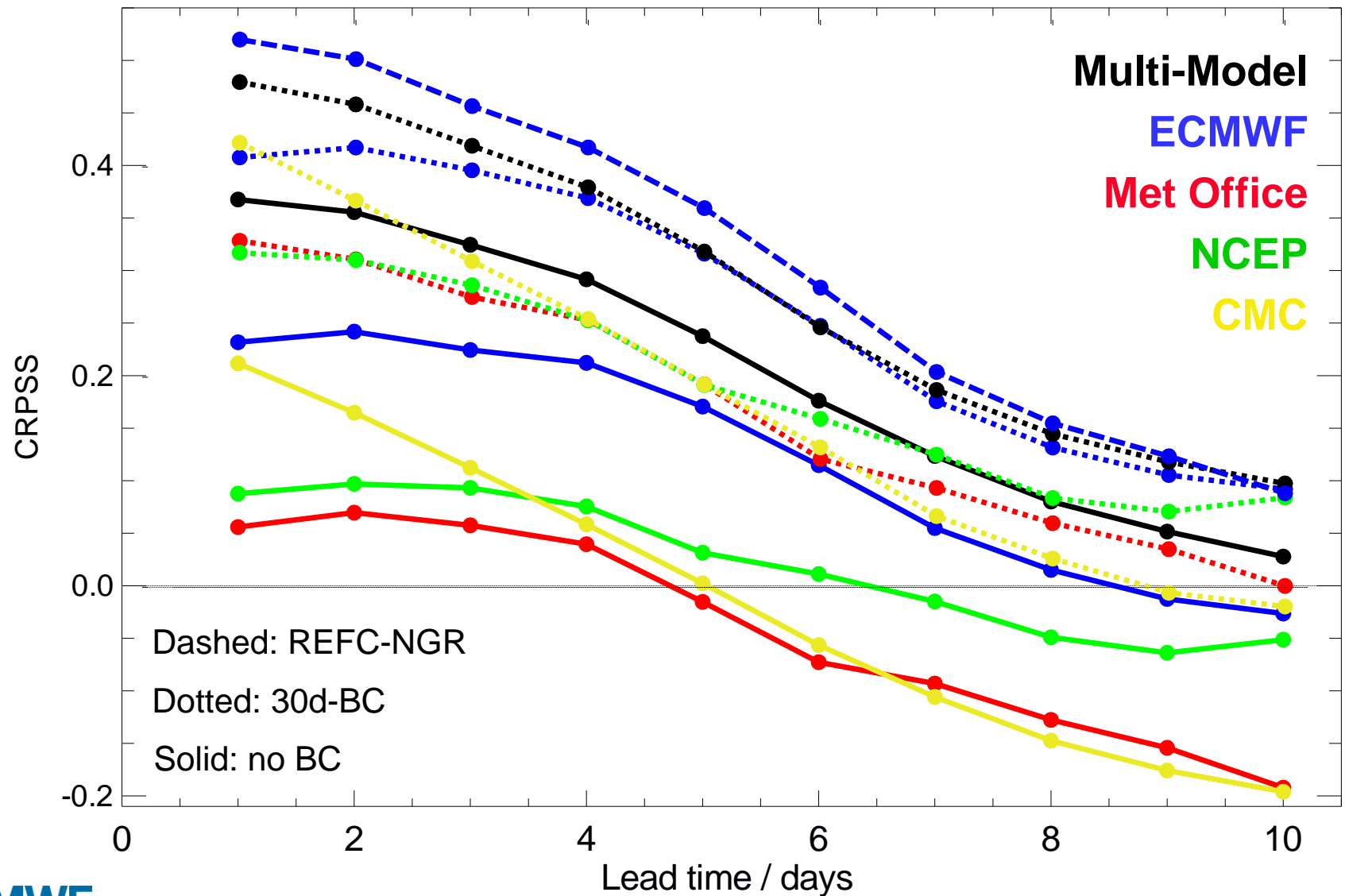


Mechanism behind improvements

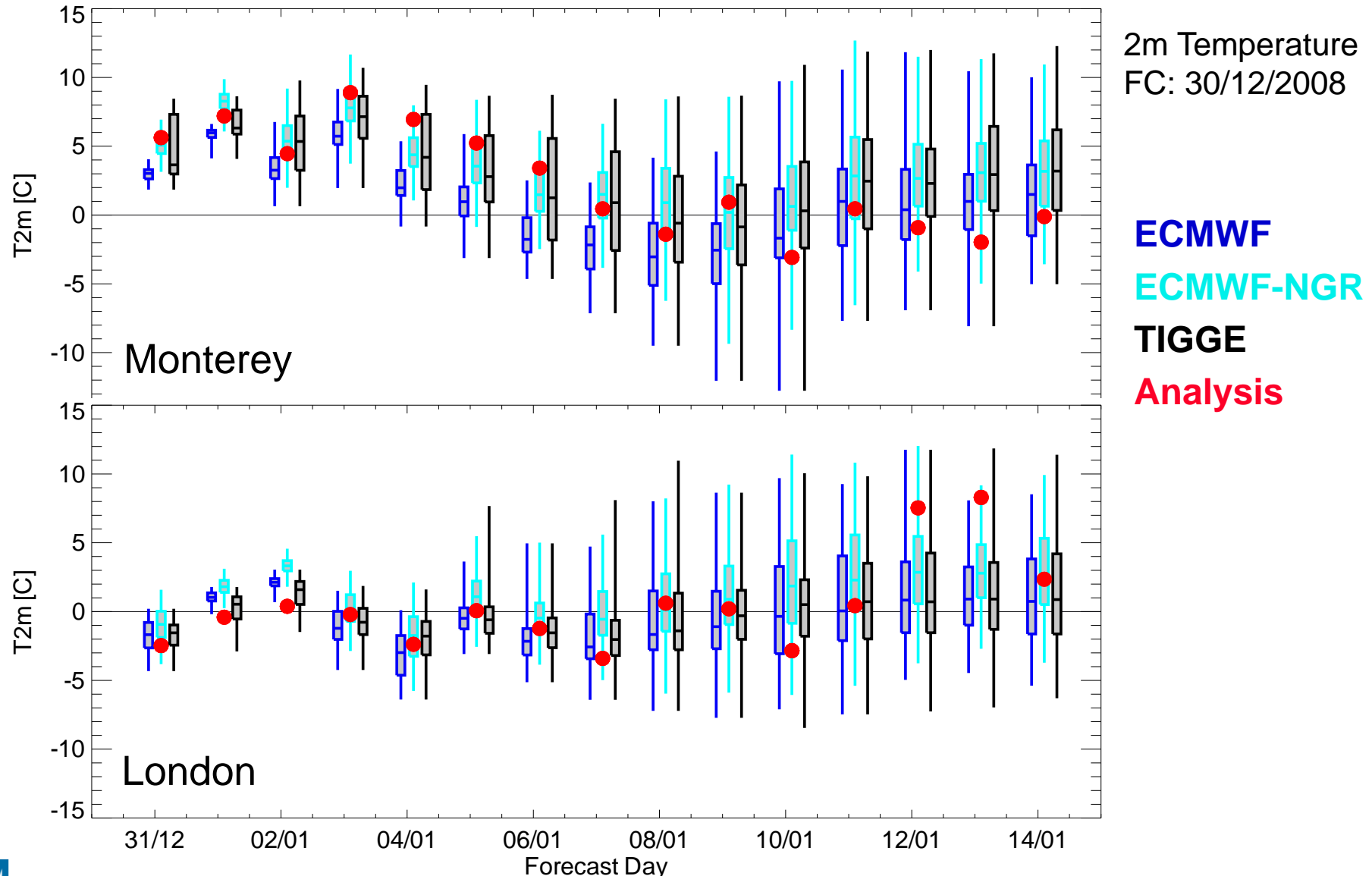


What about station data?

T-2m, 250 European stations
DJF 2008/09



Impact of calibration & MM in EPSgrams



A separate study ...

- (Reference: Hamill, 2012)
- Examining precipitation forecasts over the US
- Four high skill models; compare ECMWF “re-forecast calibrated” with multi-model (no re-forecasts)
- Conclusions:
 - “Raw multimodel PQPFs were generally more skillful than reforecast-calibrated ECMWF PQPFs for the light precipitation events but had about the same skill for the higher-precipitation events”
 - “Multimodel ensembles were also postprocessed using logistic regression and the last 30 days of prior forecasts and analyses; Postprocessed multimodel PQPFs did not provide as much improvement to the raw multimodel PQPF as the reforecast-based processing did to the ECMWF forecast.”
 - “The evidence presented here suggests that all operational centers, even ECMWF, would benefit from the open, real-time sharing of precipitation forecast data and the use of reforecasts.”

Summary on MM vs. calibration

- What are the relative benefits/costs of both approaches?
 - Both multi-model and a reforecast calibration approach can improve predictions, in particular for (biased and under-dispersive) near-surface parameters
- What is the mechanism behind the improvements?
 - Both approaches correct similar deficiencies with a similar level of improvement
- Which is the “better” approach?
 - On balance, reforecast calibration seems to be the easier option for a reliable provision of forecasts in an operational environment
 - Both approaches can be useful in achieving the ultimate goal of an optimized, well tuned forecast system

Overall summary

- The goal of calibration is to correct for known model deficiencies
- A number of statistical methods exist to post-process ensembles
- Each method has its own strengths and weaknesses
 - Analogue methods seem to be useful when large training dataset available
 - Logistic regression can be helpful for extreme events not seen so far in training dataset
 - NGR method useful when strong spread-skill relationship exists, but relatively expensive in computational time
- Greatest improvements can be achieved on local station level
- Bias correction constitutes a large contribution for all calibration methods
- ECMWF reforecasts are a very valuable training dataset for calibration

References and further reading

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