

Post-Processing of Ensemble Forecasts

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This lecture is focussed on application to medium-range forecasts, but the theory and methods are general.

- Motivation
- Methods
- Training data sets
- Results



- Raw ENS forecasts are subject to forecast bias and dispersion errors,
 i.e. uncalibrated
- The goal of calibration is to correct for such known model deficiencies, i.e. to construct predictions with statistical properties similar to the observations
- A number of statistical methods exist for post-processing ensembles
- Calibration needs a record of prediction-observation pairs
- Calibration is particularly successful at station locations with long historical data record (-> downscaling)

Calibration methods

- Bias correction
- Multiple implementation of deterministic MOS
- Ensemble dressing
- Bayesian model averaging
- Non-homogenous Gaussian regression
- Logistic regression
- Analogue method

Bias correction

• As a simple first order calibration a bias correction can be applied:

$$c = -\frac{1}{N} \sum_{i=1}^{N} \overline{e}_i + \frac{1}{N} \sum_{i=1}^{N} o_i$$

with: $\overline{e_i}$ = ensemble mean of the ith forecast o_i = value of ith observation N = number of observation-forecast pairs

- This correction is added to each ensemble member, i.e. spread is not affected
- Particularly useful/successful at locations with features not resolved by model and causing significant bias

Bias correction

Station: ULAN-UDE (# 30823, Height: 515m) Lead: 120h



Multiple implementation of det. MOS

- A possible approach for calibrating ensemble predictions is to simply correct each individual ensemble member according to its deterministic model output statistic (MOS)
- **BUT**: this approach is conceptually inappropriate since for longer lead-times the MOS tends to correct towards climatology
 - > all ensemble members tend towards climatology with longer lead-times
 - decreased spread with longer lead-times
 - in contradiction to increasing uncertainty with increasing lead-times
- (Discontinued?) experimental product at http://www.nws.noaa.gov/mdl/synop/enstxt.php, but no objective verification yet...



 Define a probability distribution around each ensemble member ("dressing")



- A number of methods exist to find appropriate dressing kernel ("bestmember" dressing, "error" dressing, "second moment constraint" dressing, etc.)
- Average the resulting n_{ens} distributions to obtain final pdf

Ensemble Dressing

• (Gaussian) ensemble dressing calculates the forecast probability for the quantiles q as:

$$P(v \le q) = \frac{1}{n_{ens}} \sum_{i=1}^{n_{ens}} \Phi \left[\frac{q - \widetilde{x}_i}{\sigma_D} \right]$$

with: Φ = CDF of standard Gaussian distribution \widetilde{x}_i = bias-corrected ensemble-member

- Key parameter is the standard deviation of the Gaussian dressing kernel
- Simple approach: "best member" dressing, take standard deviation from r.m.s. difference of (obs-best member) from training set.

Ensemble Dressing

• Common approach: second-moment constraint dressing



•BUT: this can give negative or unstable variances, if model is already near to or over-dispersive.

•Ensemble dressing to generate a pdf is only suitable for *under-dispersive* forecasts.

Bayesian Model Averaging

- BMA closely linked to ensemble dressing
- Differences:
 - It dressing kernels do not need to be the same for all ensemble members
 - different estimation method for kernels
- Useful for giving different ensemble members (models) different weights:

• Estimation of weights and kernels simultaneously via maximum likelihood, i.e. maximizing the log-likelihood function:

$$\ln(\Lambda) = -\sum_{i=1}^{N} \ln \left[w_1 g_1(v_i | \widetilde{x}_{1,i}, \sigma_1^2) + w_e \sum_{j=2}^{n_{ens}} g_e(v_i | \widetilde{x}_{j,i}, \sigma_e^2) \right] g_l, g_e = \text{Gaussian P}$$

DF's

BMA: example



BMA: recovered ensemble members



Non-homogenous Gaussian Regression

• In order to account for existing spread-skill relationships we model the variance of the error term as a function of the ensemble spread s_{ens} :

$$P(v \le q) = \Phi\left[\frac{q - (a + b\overline{x}_{ens})}{\sqrt{c + ds_{ens}^2}}\right]$$

- The parameters *a*,*b*,*c*,*d* are fit iteratively by minimizing the CRPS of the training data set
- Interpretation of parameters:

□ bias & general performance of ens-mean are reflected in *a* and *b* □ large spread-skill relationship: $c \approx 0.0$, $d \approx 1.0$ □ small spread-skill relationship: $d \approx 0.0$

 Calibration provides mean and spread of Gaussian distribution (called non-homogenous since variances of regression errors not the same for all values of the predictor, i.e. non-homogenous)

Logistic regression

• Logistic regression is a statistical regression model for Bernoullidistributed dependent variables

$$P(v \le q) = \frac{\exp(\beta_0 + \beta_1 \overline{x}_{ens})}{1 + \exp(\beta_0 + \beta_1 \overline{x}_{ens})}$$

P is bound by 0,1 and produces an s-shaped prediction curve
 steepness of curve (β₁) increases with decreasing spread, leading to sharper forecasts (more frequent use of extreme probabilities)
 parameter β₀ corrects for bias, i.e. shifts the s-shaped curve

How does logistic regression work?



* Example: LR-Probability worse!



Example: LR-Probability (much) better!



Analogue method

- Full analogue theory assumes a nearly infinite training sample
- Justified under simplifying assumptions:
 - Search only for local analogues
 - Match the ensemble-mean fields
 - Consider only one model forecast variable in selecting analogues
- General procedure:
 - > Take the ensemble mean of the forecast to be calibrated and find the n_{ens} closest forecasts to this in the training dataset
 - Take the corresponding observations to these n_{ens} re-forecasts and form a new calibrated ensemble
 - Construct probability forecasts from this analogue ensemble

Analogue method



Ref: Hamill & Whitaker, 2006, MWR

Training datasets

- All calibration methods need a training dataset, containing a number of forecast-observation pairs from the past
 - > The more training cases the better
 - The model version used to produce the training dataset should be as close as possible to the operational model version
- For research applications often only one dataset is used to develop and test the calibration method. In this case cross-validation has to be applied.
- For operational applications one can use:
 - Operational available forecasts from e.g. past 30-40 days
 - Data from a re-forecast dataset covering a larger number of past forecast dates / years

"Perfect" Reforecast Data Set

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Early motivating results from Hamill et al., 2004

Raw ensemble



The 32-day unified ENS ensemble system

- Unified ENS ensemble system enables the production of a unified reforecast data set, to be used by:
 - ➢ EFI model climate
 - ➤ 10-15 day ENS calibration
 - Monthly forecasts anomalies and verification
- Efficient use of resources (computational and operational)
- "Realistic" reforecast system has to be an optimal compromise between affordability and needs of all three applications
- Presently use 5 member ensemble, once per week, for last 20 years
- About to switch to 11 members, twice per week.

Unified ENS Reforecasts

(From 12th May 2015)

Used in EFA and SOT

Used in monthly forecast

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Testing the benefits of reforecast calibration

(Reference: Hagedorn et al, 2012)

- One goal of the TIGGE^{*} project is to investigate whether multi-model predictions are an improvement to single model forecasts
- The goal of using reforecasts to calibrate single model forecasts is to provide improved predictions
- Questions:
 - > What are the relative benefits (costs) of both approaches?
 - > What is the mechanism behind the improvements?
 - Which is the "better" approach?

* TIGGE stands for: THORPEX Interactive Grand Global Ensemble

Comparing 9 TIGGE models & the MM



Comparing 4 TIGGE models & the MM



Comparing 4 TIGGE models, MM, EC-CAL



Comparing 4 TIGGE models, MM, EC-CAL



Mechanism behind improvements



Mechanism behind improvements



Mechanism behind improvements



What about station data?

T-2m, 250 European stations DJF 2008/09



Impact of calibration & MM in EPSgrams



A separate study ...

(Reference: Hamill, 2012)

- Examining precipitation forecasts over the US
- Four high skill models; compare ECMWF "re-forecast calibrated" with multi-model (no re-forecasts)
- Conclusions:
- "Raw multimodel PQPFs were generally more skillful than reforecast-calibrated ECMWF PQPFs for the light precipitation events but had about the same skill for the higher-precipitation events"
- "Multimodel ensembles were also postprocessed using logistic regression and the last 30 days of prior forecasts and analyses; Postprocessed multimodel PQPFs did not provide as much improvement to the raw multimodel PQPF as the reforecast-based processing did to the ECMWF forecast."
- "The evidence presented here suggests that all operational centers, even ECMWF, would benefit from the open, real-time sharing of precipitation forecast data and the use of reforecasts."

Summary on MM vs. calibration

- What are the relative benefits/costs of both approaches?
 - Both multi-model and a reforecast calibration approach can improve predictions, in particular for (biased and under-dispersive) near-surface parameters
- What is the mechanism behind the improvements?

> Both approaches correct similar deficiencies to a similar extent

- Which is the "better" approach?
 - On balance, reforecast calibration seems to be the easier option for a reliable provision of forecasts in an operational environment
 - Both approaches can be useful in achieving the ultimate goal of an optimized, well tuned forecast system

Coverall summary

- The goal of calibration is to correct for known model deficiencies
- A number of statistical methods exist to post-process ensembles
- Each method has its own strengths and weaknesses
 - Analogue methods seem to be useful when large training dataset available
 - Logistic regression can be helpful for extreme events not seen so far in training dataset
 - NGR method useful when strong spread-skill relationship exists, but relatively expensive in computational time
- Greatest improvements can be achieved on local station level
- Bias correction constitutes a large contribution for all calibration methods
- ECMWF reforecasts are a very valuable training dataset for calibration

References and further reading

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