

# Ensemble Verification I

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Training Course 2015

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- 2 reliability (statistical consistency)
- 3 dichotomous predictands (yes/no)
  - ▶ contingency tables
  - ▶ Brier score
  - ▶ relative operating characteristic (ROC)
  - ▶ logarithmic score
- 4 sensible probabilities:  $p=0$  and  $p=1$ ?

# Objectives of verification (... evaluation and diagnostics)

Assess the quality of a forecast system for

- administrative purposes
  - ▶ tool to monitor the system
- scientific/diagnostic purposes
  - ▶ Identify strengths and weaknesses of a forecast system
  - ▶ Guide the future development of a forecast system
- economic purposes/ support for decision making
  - ▶ Whether a forecast is useful or valuable for a specific user depends on error characteristics but also what other information the user has (eg. climatology) and the particular decision that (s)he needs to make.
  - ▶ An accurate forecast can be of little value (blue desert sky)
  - ▶ An inaccurate forecast can be of high value (an intense storm that is predicted but with position error)
  - ▶ The actual forecast value may differ from the potential forecast value (availability of relevant fc information, user's constraints: economic, time limits, lack of training, etc.)

# Concepts

## Forecast attributes and forecast skill

- Forecast verification is the investigation of the properties of the **joint distribution of forecasts and observations** (Murphy & Winkler 1987)
- Scalar aspects (attributes) of the forecast quality include:
  - ▶ accuracy (e.g. mean absolute error, mean squared error, threat score)
  - ▶ bias
  - ▶ reliability
  - ▶ resolution
  - ▶ discrimination
  - ▶ sharpness (property of forecast only, e.g. ensemble spread)
- Forecast skill: relative accuracy of one forecast system with respect to a reference forecast (e.g. climatology)
- More generally: observations → estimates of the true state (e.g. also analyses)

## Concepts (II)

Examples of scores for single forecasts

sample of  $N$  forecast-observation pairs  $(x_j, y_j)$ :

- root mean square error  $\left( \frac{1}{N} \sum_{j=1}^N (x_j - y_j)^2 \right)^{1/2}$
- mean absolute error  $\frac{1}{N} \sum_{j=1}^N |x_j - y_j|$
- mean error  $\frac{1}{N} \sum_{j=1}^N (x_j - y_j)$
- anomaly correlation coefficient
- scores for dichotomous events (e.g. rain/no rain)
  - ▶ Peirce skill score (= Hansen-Kuipers, true skill statistic)
  - ▶ Gilbert skill score (Equitable threat score)
  - ▶ frequency bias
- All of these scores can be applied to the ensemble mean.

# Concepts (III)

## Probabilistic forecasts and ensemble forecasts

- The ensemble predicted rain with a probability of 10%.
- It did rain on the day
- Is this a good forecasts?
  - ▶ Yes
  - ▶ No
  - ▶ I don't know

For probabilistic forecast, the prediction (an ensemble or a probability distribution) and the observation (a value) are different objects. The distribution is not known more precisely after the verifying observation becomes available.

# Classification

- by predicted object
  - ▶ discrete set of events: e.g. cloudy/clear sky; rain/no rain; temperature in lower, middle or upper tercile . . .
  - ▶ continuous scalar variable: temperature in London
  - ▶ continuous field: 2-metre temperature field in Europe; profile of wind at Frankfurt airport
- discrete sample (an ensemble) or probability distribution
  - ▶ ensemble predicts 50 values of temperature in London
  - ▶ probability distribution for temperature in London fitted to an ensemble of forecasts
  - ▶ probability distribution of temperature in London determined from a single forecast + a fit of a Gaussian distribution to past errors of this single forecast.
  - ▶ climatological probability distribution estimated from reanalyses

# Statistical consistency and reliability

- Are the true values (or observations) statistically indistinguishable from the members of the ensemble?
  - Measures to assess reliability
    - ▶ bias
    - ▶ “spread” versus “error”
    - ▶ rank histogram
    - ▶ reliability diagram (for dichotomous (binary) prediction, e.g. rain/no rain or 0/1)
- definitions and examples . . .
- Reliability alone does not imply skill. The climatological distribution is perfectly reliable for a stationary climate.

## Reliability of the ensemble spread

- Consider ensemble variance (“spread”) for an  $M$ -member ensemble

$$\frac{1}{M} \sum_{j=1}^M (x_j - \bar{x})^2$$

and the squared error of the ensemble mean

$$(\bar{x} - y)^2$$

- Average the two quantities for many locations and/or start times.
- The averaged quantities have to match for a reliable ensemble (within sampling uncertainty).
- Finite ensemble size can be corrected for in the estimation of the error of the ensemble mean and the ensemble variance.
- **Cave:** Even in a perfect ensemble, the correlation of ensemble spread and rms error is not 1.



# Examples of spread and error

## ECMWF EPS — 500 hPa geopotential

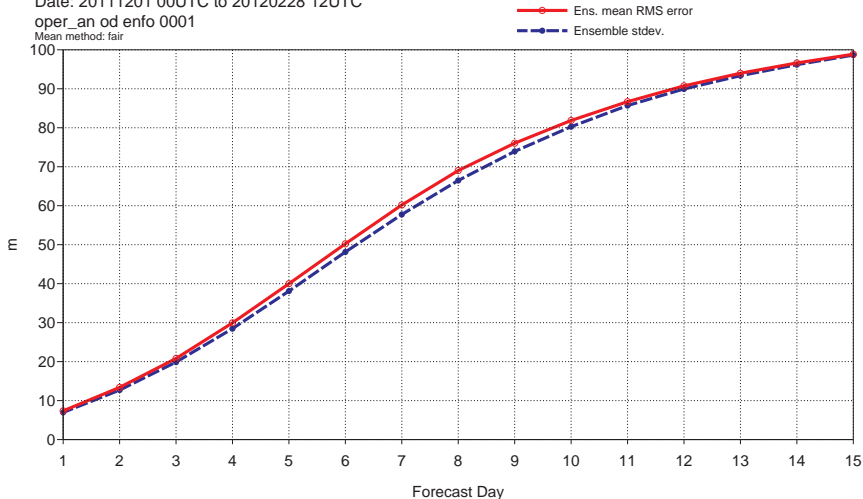
500hPa geopotential

NHem Extratropics (lat 20.0 to 90.0, lon -180.0 to 180.0)

Date: 20111201 00UTC to 20120228 12UTC

oper\_an od enfo 0001

Mean method: fair



# Examples of spread and error

## ECMWF EPS — mean sea level pressure

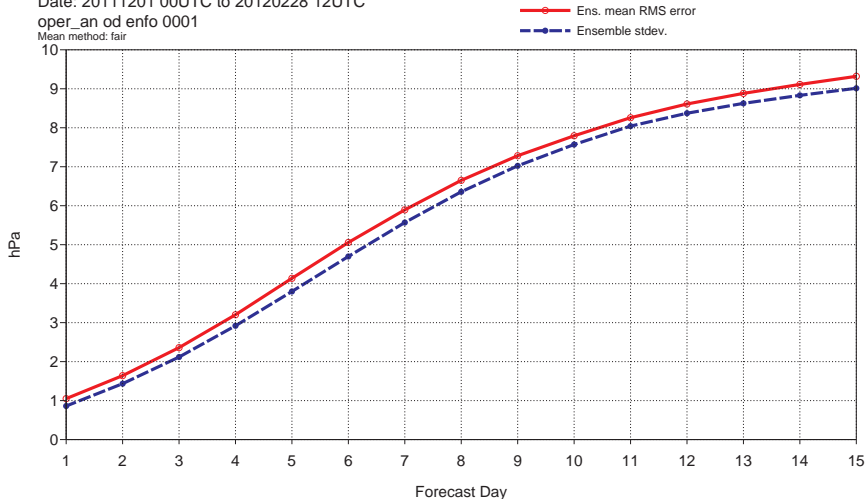
Mean sea level pressure

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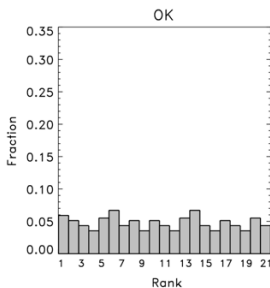


# Rank Histogram

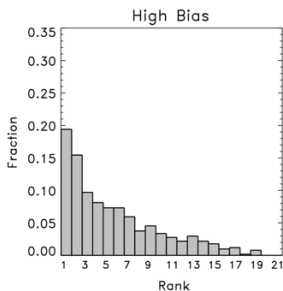
- Are the ensemble members statistically indistinguishable from the verification data?
- Determine where **observation** lies with respect to the ensemble members:



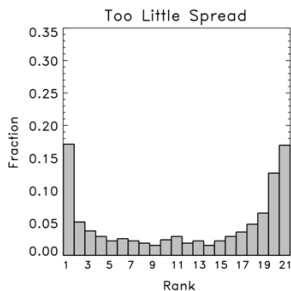
# Rank Histogram



OBS is indistinguishable from any other ensemble member



OBS is too often below the ensemble members (biased forecast)



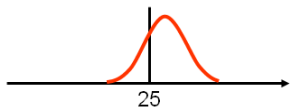
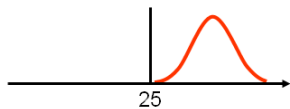
OBS is too often outside the ensemble spread

A uniform rank histogram is a necessary but not sufficient criterion for determining that the ensemble is reliable (see also: T. Hamill, 2001, MWR)

# Dichotomous predictands

## Joint distribution of forecasts and obs

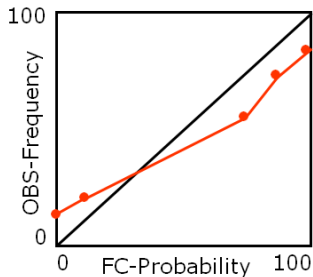
- Consider the probabilistic prediction of the event that the temperature exceeds  $25^{\circ}$  C.
- Hypothetical verification sample of 30 start dates and 2200 grid points = 66000 forecasts.
- How often was the event ( $T > 25^{\circ}$  C) predicted with probability  $p$ ?



FC Prob.	# FC	OBS-Frequency (perfect model)	OBS-Frequency (imperfect model)
100%	8000	8000 (100%)	7200 (90%)
90%	5000	4500 (90%)	4000 (80%)
80%	4500	3600 (80%)	3000 (66%)
....	....	....	....
....	....	....	....
....	....	....	....
10%	5500	550 (10%)	800 (15%)
0%	7000	0 (0%)	700 (10%)

# Dichotomous predictands

## Reliability diagram

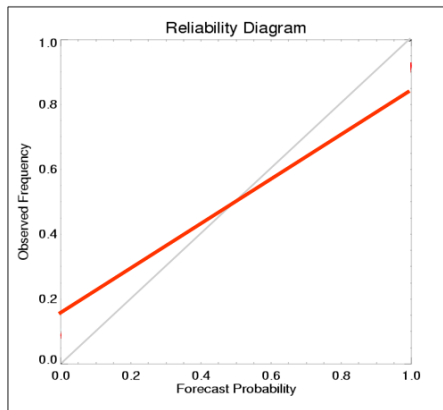


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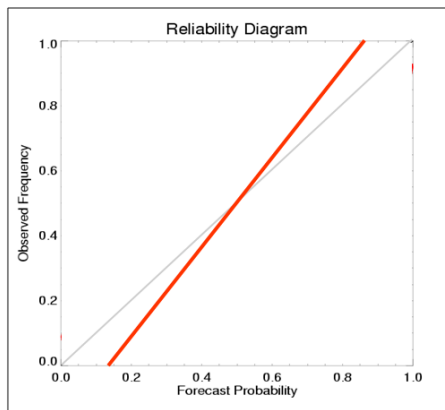
# Over- and under-confidence

## Reliability diagram

over-confident model



under-confident model



# Scores for dichotomous predictions

- Extended contingency tables
- Scores
  - ▶ Brier score (reliability and resolution)
  - ▶ Logarithmic score (reliability and resolution)
  - ▶ Relative Operating Characteristic (discrimination)



# Contingency table

single forecast

- Consider an event  $e$  (e.g.  $T > 25^\circ \text{ C}$ )
- The joint distribution of forecasts and observations can be condensed in a  $2 \times 2$  contingency table:

$e$ predicted	$e$ observed	
	Yes	No
Yes	hits $a$	false alarms $b$
No	misses $c$	correct rejections $d$

- hit rate  $H = \frac{a}{a+c}$
- false alarm rate  $F = \frac{b}{b+d}$
- $N = a + b + c + d$  sample size

# (Extended) contingency table

ensemble

The joint distribution of forecasts and observations for a  $M$ -member ensemble can be summarized in a  $(M + 1) \times 2$  contingency table  $\mathbf{T}$

$$\text{sample size } N = \sum_{j=0}^M n_j + \sum_{j=0}^M \tilde{n}_j$$

Each row corresponds to a probability value, e.g.

$$p = j/M \rightarrow$$

$e$ pred. by $m_e$ members	$e$ observed	
	Yes	No
$M$	$n_M$	$\tilde{n}_M$
$M - 1$	$n_{M-1}$	$\tilde{n}_{M-1}$
...	...	...
$j$	$n_j$	$\tilde{n}_j$
...	...	...
1	$n_1$	$\tilde{n}_1$
0	$n_0$	$\tilde{n}_0$

Contingency tables are additive:

$$\mathbf{T}(\text{sample1} \cup \text{sample2}) = \mathbf{T}(\text{sample1}) + \mathbf{T}(\text{sample2})$$

# Brier score

## definition and decomposition

$$\text{BS} = \frac{1}{N} \sum_{k=1}^N (p_k - o_k)^2$$

- $p_k$  is the predicted probability of the  $k$ -th forecast and  $o_k = 1$  (0) if the event occurred (did not occur)
- The Brier score BS is the **mean squared error** of the probability forecast.
- The BS can be decomposed in three components that measure
  - ▶ reliability
  - ▶ resolution
  - ▶ uncertainty

# Brier score components

$$BS = REL - RES + UNC$$

stratify sample in terms of the rows  $j$  in the contingency table

Reliability: deviation of observed relative frequency from forecasted probability

$$REL = \frac{1}{N} \sum_{j=0}^M \ell_j (\bar{o}_j - p_j)^2$$

Resolution: ability of forecast to identify periods in which observed frequencies differ from average

$$RES = \frac{1}{N} \sum_{j=0}^M \ell_j (\bar{o}_j - \bar{o})^2$$

Uncertainty: Variance of obs. (0/1) in sample

$$UNC = \bar{o}(1 - \bar{o})$$

- $N$  total number of cases
- $M$  number of probability bins  $-1$
- $p_j = j/M$  probability in bin  $j$
- $\ell_j = n_j + \tilde{n}_j$  number of cases in bin  $j$
- $\bar{o}_j = n_j/\ell_j$  frequency of event occurring when forecasted with probability  $p_j$
- $\bar{o}$  event frequency in whole sample

# Brier Skill Score

- Skill scores are used to compare the performance of forecasts with that of a reference forecast (e.g. climatological distribution)
- They are defined so that the perfect forecast has a skill score of 1 and the reference forecast has the skill score of 0

$$\text{skill score} = \frac{\text{actual fc} - \text{ref}}{\text{perfect fc} - \text{ref}}$$

- BS for perfect forecast is 0  $\Rightarrow$

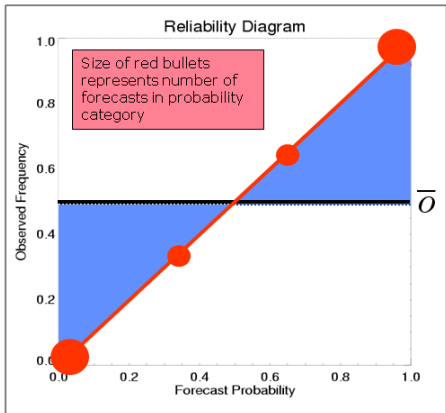
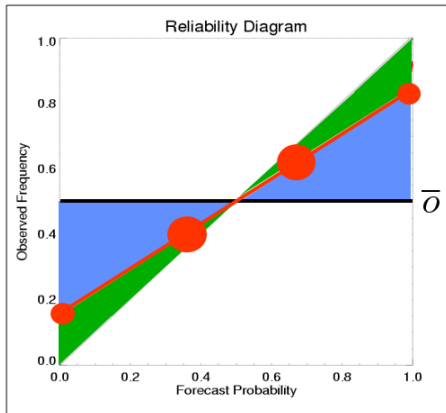
$$\text{BSS} = 1 - \frac{\text{BS}}{\text{BS}_{\text{ref}}}$$

- positive (negative) BSS  $\Rightarrow$  forecast is better (worse) than the reference forecast

# Brier score

## Attributes diagram

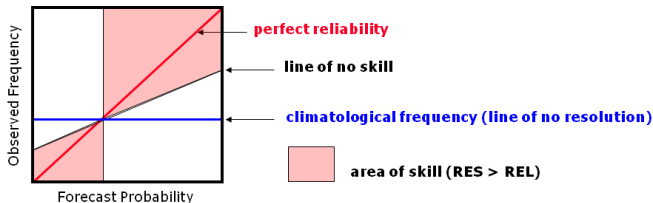
- Reliability score (the smaller, the better)
- Resolution score (the bigger, the better)



# Positive contribution to skill

diagnosed from the attributes diagram

$$\begin{aligned} BSS &= 1 - \frac{BS}{BS_c} \\ &= 1 - \frac{REL - RES + UNC}{UNC} = \frac{RES - REL}{UNC} \end{aligned}$$



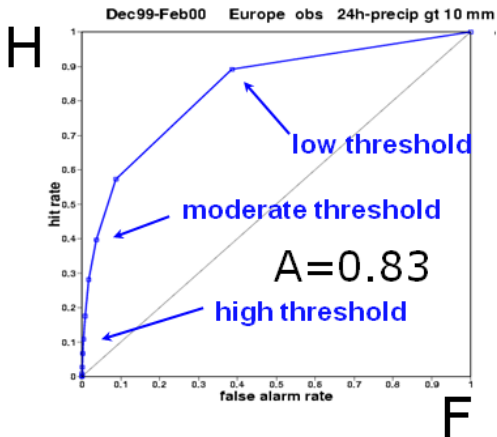
Cave: Using sample climatology as reference can lead to fictitious skill

# Discrimination and ROC

- until now, we looked at question:  
What is the distribution of observations  $o$  if the forecast system predicts an event to occur with probability  $p$ ?
- To measure the ability of a forecast system to *discriminate* between occurrence and non-occurrence of an event, one has to ask:  
What distributions of probabilities have been predicted when the event occurred and when it did not occur?
- For any probability threshold  $p_i$  one can then determine the hit rate  $H_i = \frac{a}{a+c}$  and the false alarm rate  $F_i = \frac{b}{b+d}$
- The *relative operating characteristic* (ROC, also referred to as receiver operating characteristic) is the diagram that shows  $H$  versus  $F$  for all probability thresholds.



# Relative Operating Characteristic



- random forecast (independent of observed event) on diagonal
- summary measure: area under the ROC  $\in [0.5, 1]$

## Logarithmic score

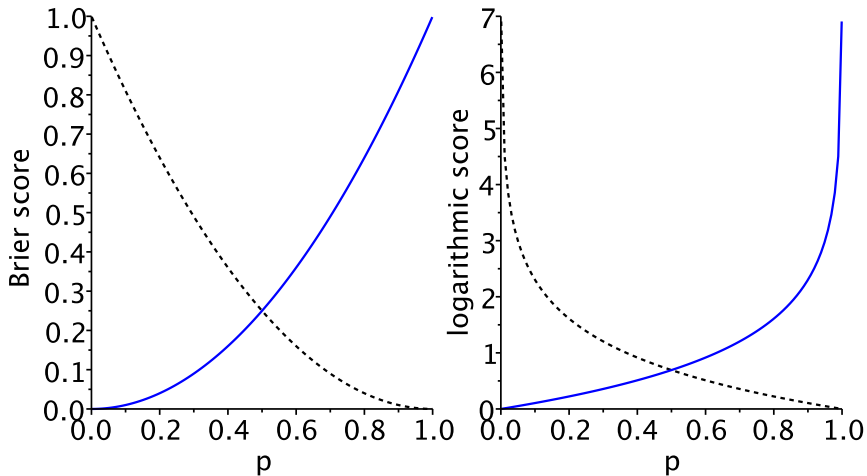
- also known as ignorance score (Good 1952, Roulston and Smith 2002)

$$\text{LS} = -\frac{1}{N} \sum_{k=1}^N [o_k \log p_k + (1 - o_k) \log(1 - p_k)]$$

- The score ranges between 0 and  $\infty$ . The latter happens if the predicted probability is zero and the event occurs (or if  $p = 1$  and the event does not occur).
- The ignorance score is more sensitive to the cases with probability close to 0 and close to 1 than the Brier score.

# Brier score versus logarithmic score

event occurs (dotted), event does not occur (solid)  
 $(p - 1)^2$  and  $p^2$        $-\log(p)$  and  $-\log(1 - p)$



## Sensible probabilities

- Never forecast  $p = 0$  or  $p = 1$  unless you are really certain!
- If the true probability is not equal to zero (or one), there will still be cases when no member (or all members) predict(s) the event. Sampling uncertainty!
- Wilks proposed to estimate cumulative probabilities using Tukey's plotting positions



- When  $n$  members of an  $M$ -member ensemble have a value less than the threshold  $\theta$ , the probability to not exceed  $\theta$  is set to

$$p^{(T)}(n) = \frac{n + 2/3}{M + 4/3}$$

- Consider for example  $M = 10$ :

n	0	1	2	3	4	5	6	7	8	9	10
p	0.06	0.15	0.24	0.32	0.41	0.50	0.59	0.68	0.76	0.85	0.94