

Calibration with MOS at DWD

ECMWF Calibration Meeting
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Reinhold Hess, Jenny Glashof, Cristina Primo
Deutscher Wetterdienst

Calibration with MOS at DWD

■ Outline

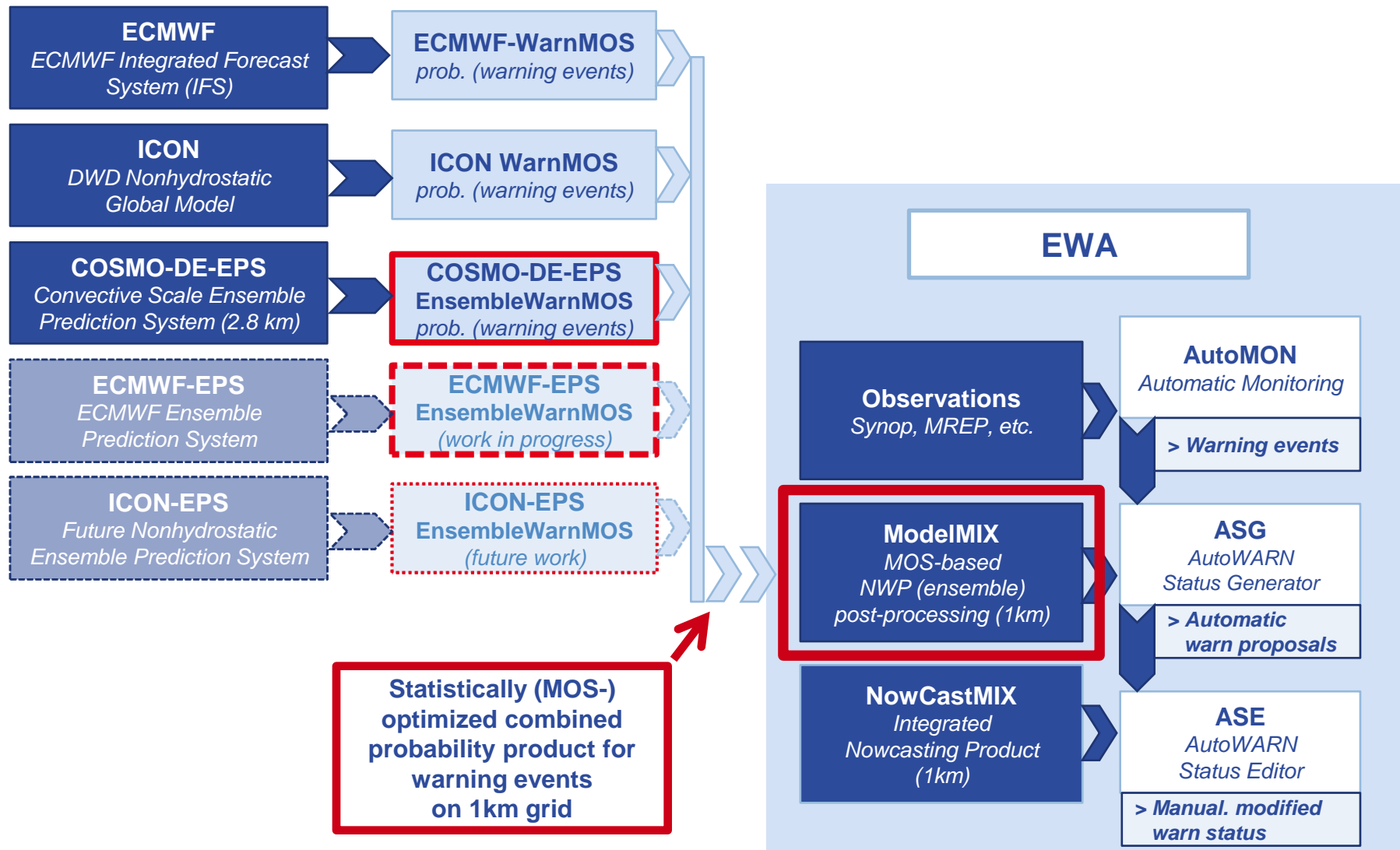
- Overview of MOS Systems at DWD
- Ensemble MOS
- ModelMIX: MOS of MOS
- Ensemble MOS for ECMWF-EPS (TIGGE/THORPEX data)
 - Verification
- Bonus



EWA: ModelMIX

decision support for weather warnings

Deutscher Wetterdienst
Wetter und Klima aus einer Hand



MOS Systems at DWD

■ Operational Systems at DWD

■ **ICON-MOS, ECMWF-MOS, MOS-MIX**

global, medium scale, at synoptic stations, based on ICON and IFS/ECMWF

■ **ICON-WarnMOS, ECMWF-WarnMOS, WarnMOS-MIX**

provides 27 warning criteria on 1x1 km grid for Germany

■ **AUTO-TAF** specialised forecasts for airports

■ **CellMOS** nowcasting thunderstorms on advecting cells (Lagrange)

■ **Ensemble-MOS, ModelMIX** (*in development, based on WarnMOS*)

calibration of ensemble forecasts (COSMO-DE-EPS, ECMWF-EPS, ICON-EPS)

Ensemble-MOS

- Enhancement of MOS Systems for Ensembles
 - apply for COSMO-DE-EPS and EZMW-EPS (later ICON-EPS)
 - optimization, calibration and interpretation using synoptical observations
 - ensemble products as model predictors
 - ensemble mean and stddev (quantiles, etc.)
 - surrounding of stations (mean and stddev of surrounding)
 - linear regression for continuous forecast elements (e.g. 2m temperature)
 - logistic regression for probabilistic forecast elements (e.g. prob(RR>15mm))
 - use of long time series, e.g. 3 years for COSMO-DE-EPS
 - multistation approach (9 climatological cluster in Germany, currently redesigned)
 - multi time equations for extreme and rare events (wind gusts, precipitation with high thresholds)
 - gauge adjusted radar data alternatively to precipitation observations
 - forecast of forecast errors, forecast uncertainty

MOS: stepwise linear and logistic regression

- provide set of predictors, e.g. model forecasts, observations, derived predictors (e.g. sqrt RR, Rel_Div_10m, CAPE index, etc.)
- select predictor with highest statistical correlation to predictand
- select further predictors correlated to residuum, as long as statistically significant

- **example: 2m temperature**

- based on 3 UTC issue of COSMO-DE-EPS

- *_MS: medium scale: 28 km*

- *_LS: large scale: 54 km*

- **Co:** coefficient of regression

- **Wgt:** normalised weight of predictor in equation

- 1 equation for each predictand (about 160), cluster (9), forecast time (21), season (4), issue of EPS(8)

```
99903 Issue=02:00z +001:00
TTT Season: spr
```

Name	Lin	Reg	1	Co	Wgt
T_G_MS				0.05	5
TD_2M_LS				-0.02	2
TTT(-1)Obs				0.88	78
Td(+0)StF				0.08	7
...					
Const. =	-5.2	RMSE =			6.28

forecast time: 1h



MOS: stepwise linear and logistic regression

- provide set of predictors, e.g. model forecasts, observations, derived predictors (e.g. sqrt RR, Rel_Div_10m, CAPE index, etc.)
- select predictor with highest statistical correlation to predictand
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- 1 equation for each predictand (about 160), cluster (9), forecast time (21), season (4), issue of EPS(8)

```
99903 Issue=02:00z +019:00
TTT Season: spr

Name      Lin Reg  1      Co      Wgt
-----
T_2M_MS           0.12     11
TD_2M_MS          0.05      4
TTT(-24)Obs       0.05      4
TTT(-1)StF        0.77     65
Cos_Dag           0.02      2
...
-----
Const. = -11.3  RMSE = 13.47
```

forecast time: 19h



Forecast of Forecast Errors (of MOS forecast)

- compute regression of any forecast element
- use MAE of residuum as predictand
- compute regression of this predictand
- **example: MAE of 2m temperature**
 - based on 12 UTC issue of ECMWF-EPS (TIGGE/THORPEX data, 4 variables)

```
99906 Issue=12:00z +024:00
TTT Season: win
```

Name	Lin	Reg	1	Co	Wgt
temp				1.04	88
Cos_Dag				0.07	3
temp_dev				0.04	3
Sin_3*Dag				0.01	3
wind				-0.16	3

```
Const. = -2.5 RMSE = 10.90 T2m
```

```
99906 Issue=12:00z +024:00
E_TTT Season: win
```

Name	Lin	Reg	1	Co	Wgt
temp_dev				0.05	37
wind				-0.19	29
temp				-0.02	18
Sin_3*Dag				-0.01	16

```
Const. = 9.3 RMSE = 7.10 MAE of T2m
```

- *temp*: ensemble mean of temperature
- *temp_dev*: standard deviation of ensemble

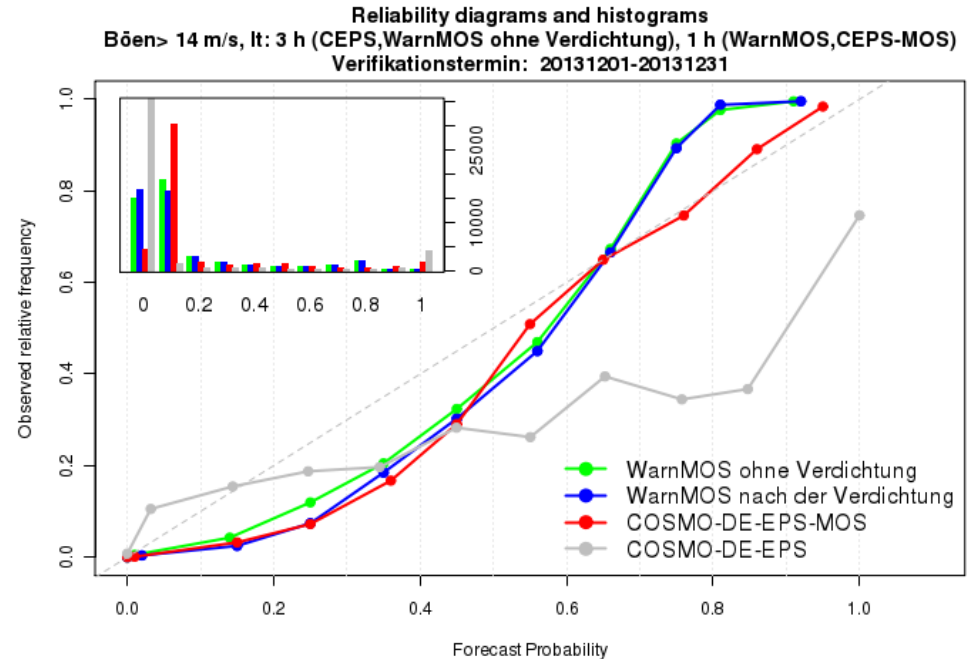
stddev is increased and calibrated
(stddev = MAE/0.8 for Gaussian distribution)



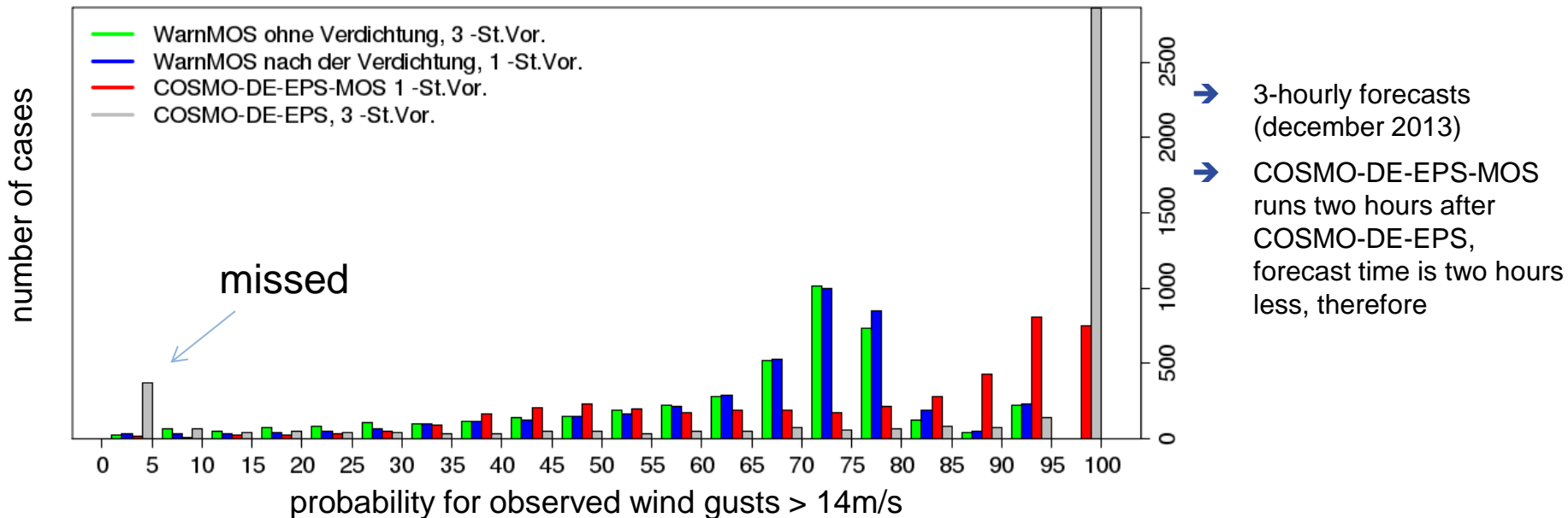
Calibration of wind gusts $> 14\text{m/s}$

Impact of logistic regression

- reliability diagram for 3-hourly forecasts
 - COSMO-DE-EPS (not calibrated, grey) shows significant overforecasting for high probabilities.
 - MOS with linear regression (blue, green) shows underforecasting for high probabilities.
 - Ensemble MOS with logistic regression (red) is correcting, however not yet perfectly. Still overforecasting for small probabilities (problem found).



threshold probabilities for observed wind gusts > 14m/s

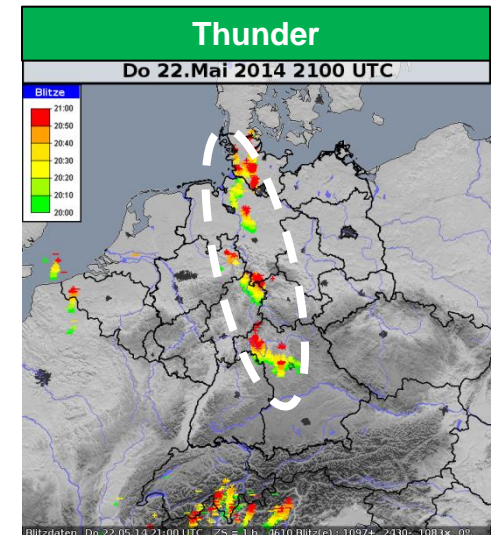
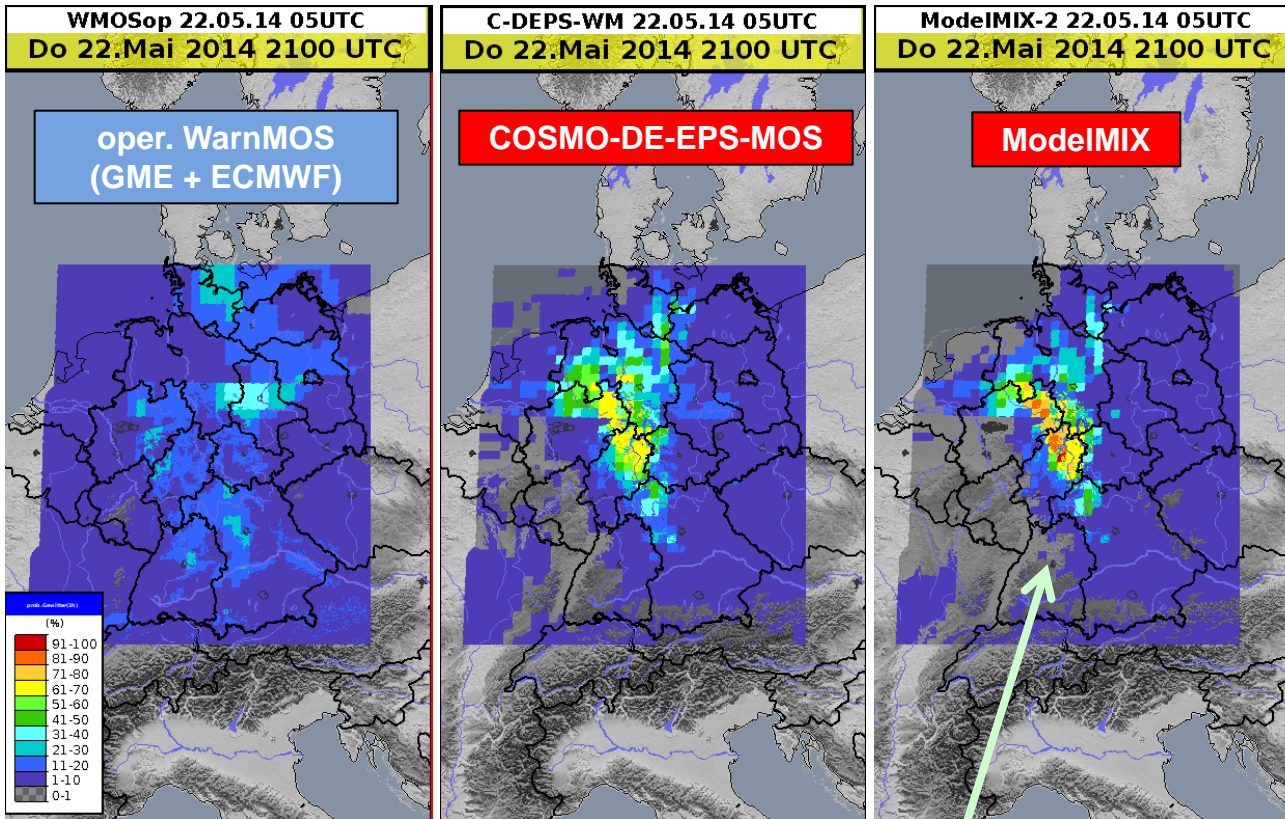


- COSMO-DE-EPS (grey) has many cases with probability 0, despite observed wind gusts >14m/s
- COSMO-DE-EPS-MOS corrects „U-shape“ of COSMO-DE-EPS

ModelMix – MOS of MOS

- combination of MOS systems
 - ICON-WarnMOS
 - ECMWF-WarnMOS
 - COSMO-DE-EPS-WarnMOS
 - ECMWF-EPS-WarnMOS
 - ...
- statistically optimal combinations
- consistent probabilistic products for warning criteria
- at locations of stations and on 1km-grid

Probability for thunderstorm +16h



Combination of MOS forecasts



signal for thunderstorm is enhanced

ModelMIX: weights of the individual MOS Systems

- ➔ mix of 2 x COSMO-DE-EPS-MOS, GME-MOS und ECMWF-MOS (latest issues)
- ➔ relative weights according to linear regression
- ➔ **example: T2m** – all seasons, alle forecast times up to 21h, all stations

Ausgabezeit	C-EPS 00h	C-EPS 03h	C-EPS 06h	C-EPS 09h	C-EPS 12h	C-EPS 15h	C-EPS 18h	C-EPS 21h	GME 00h	GME 12h	EZMW 00h	EZMW 12h
02h	74%							3%		2%		21%
05h	24%	54%							6%			16%
08h		21%	62%						3%			14%
11h			35%	44%					2%		19%	
14h				29%	53%				1%		17%	
17h					30%	49%				8%	13%	
20h						18%	62%			6%	14%	
23h							4%	62%		2%		32%

ModelMIX: weights of the individual MOS Systems

- ➔ mix of 2 x COSMO-DE-EPS-MOS, GME-MOS und ECMWF-MOS (latest issues)
- ➔ relative weights according to linear regression
- ➔ **example: FX/1h>25kn** – all seasons, alle forecast times up to 21h, all stations

Ausgabezeit	C-EPS 00h	C-EPS 03h	C-EPS 06h	C-EPS 09h	C-EPS 12h	C-EPS 15h	C-EPS 18h	C-EPS 21h	GME 00h	GME 12h	EZMW 00h	EZMW 12h
02h	39%							28%		7%		25%
05h	8%	44%							24%			24%
08h		6%	53%						16%			25%
11h			13%	45%					13%		30%	
14h				10%	52%				10%		38%	
17h					10%	49%				22%	18%	
20h						11%	59%			14%	16%	
23h							13%	54%		4%		29%

ModelMIX: weights of the individual MOS Systems

- mix of 2 x COSMO-DE-EPS-MOS, GME-MOS und ECMWF-MOS (latest issues)
- relative weights according to linear regression
- **example: RR/1h>15mm** – all seasons, alle forecast times up to 21h, all stations

Ausgabezeit	C-EPS 00h	C-EPS 03h	C-EPS 06h	C-EPS 09h	C-EPS 12h	C-EPS 15h	C-EPS 18h	C-EPS 21h	GME 00h	GME 12h	EZMW 00h	EZMW 12h
02h	54%							22%		14%		11%
05h	31%	45%							17%			7%
08h		43%	44%						6%			7%
11h			30%	43%					9%		17%	
14h				22%	57%				8%		13%	
17h					34%	35%				20%	11%	
20h						26%	56%			8%	9%	
23h							25%	43%		10%		22%

Ensemble-MOS for ECMWF-EPS

■ TIGGE/THORPEX data

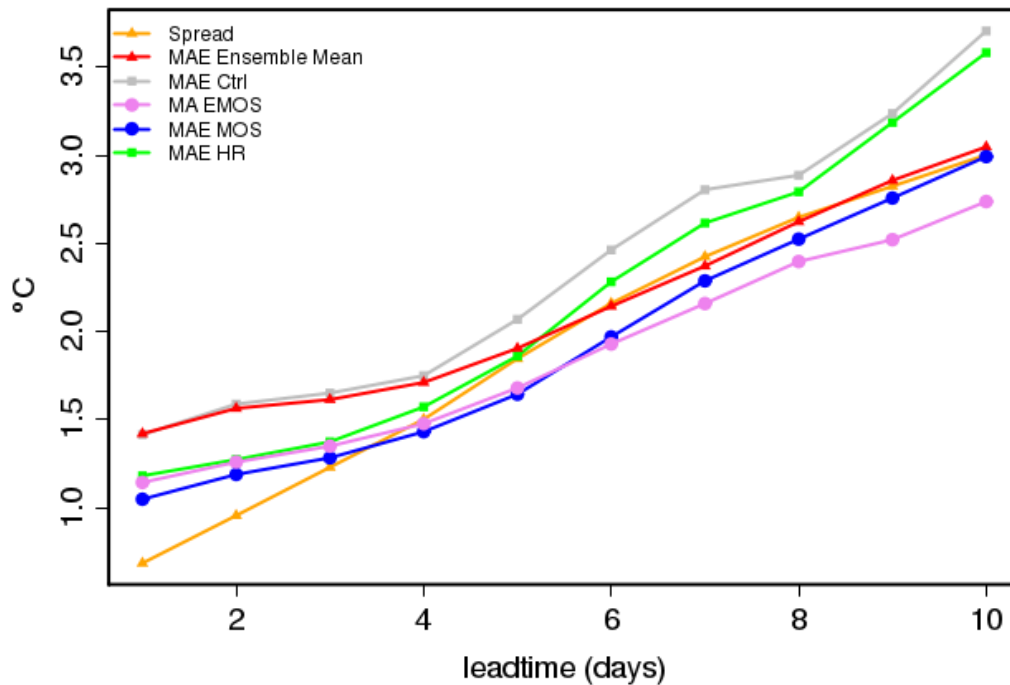
■ 36 TIGGE stations

- 50 ensembles, 1 high resolution run
- 2m temperatur, mean wind, cloud coverage, 24h precipitation
 - observations as predictands
 - ensemble products, mean, stddev as predictors
- training sample 2002-2012 (10 years)
- free forecasts for 2013
 - variables and errors (smoke plumes, „Rauchfahnen“)
 - verification

EnsembleMOS for ECMWF-EPS

■ Verification of 2013 – 2m temperature errors

Comparison of Ensemble, MOS, High Res. and Control of Temperature in Frankfurt (20130102 - 20140110)



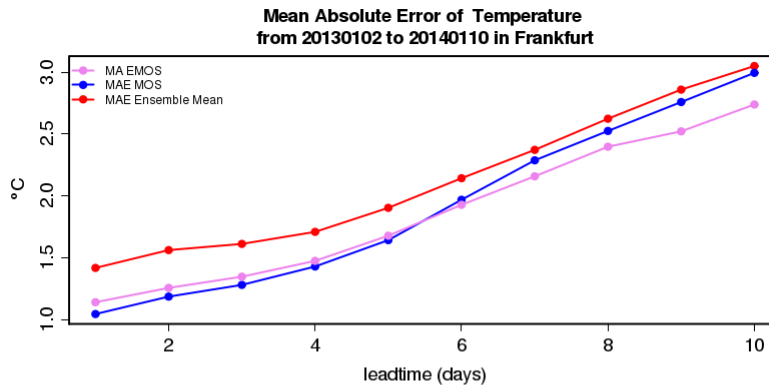
Frankfurt

MAE MOS: MOS Errors (blue)
MA EMOS: Estimated Errors (pink)

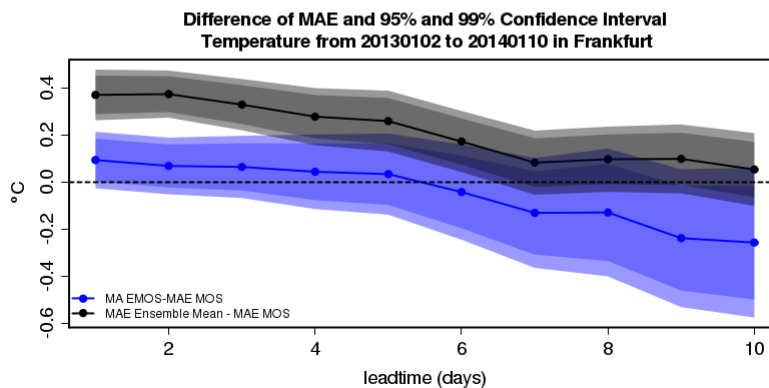
EnsembleMOS for ECMWF-EPS

■ Verification of 2013 – 2m temperature errors

Frankfurt



MAE MOS: MOS Errors (blue)
MA EMOS: Estimated Errors (pink)



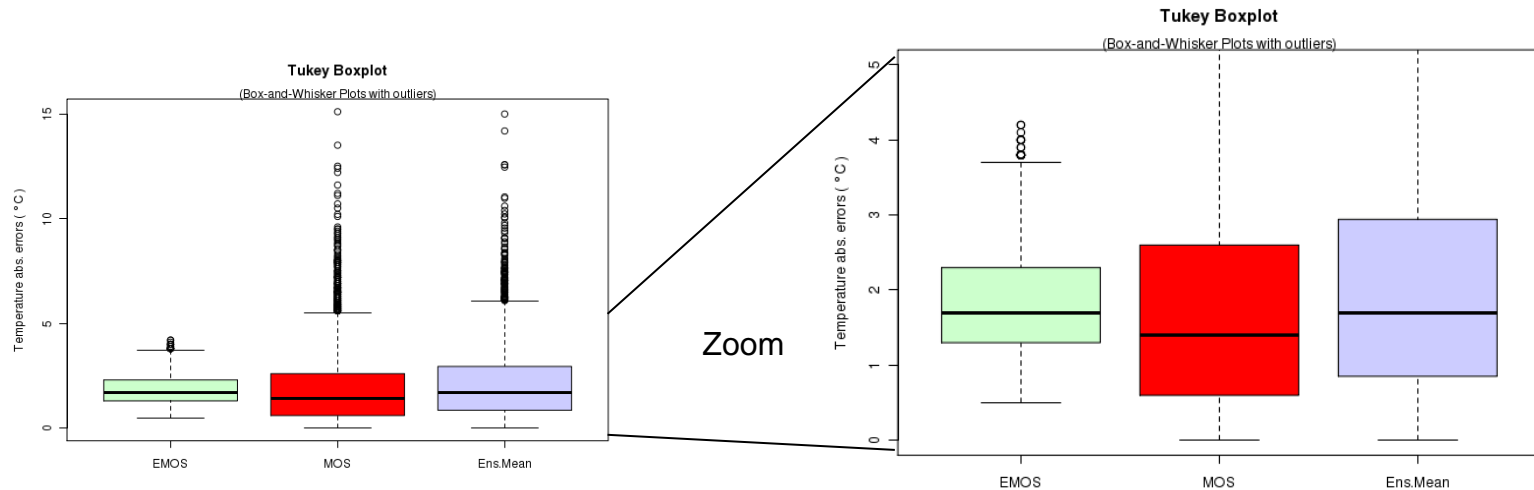
Ensemble-MOS (black):
significantly better until day 6

Estimated-True Errors (blue):
no significant difference

EnsembleMOS for ECMWF-EPS

■ Verification of 2013 – 2m temperature errors

Frankfurt



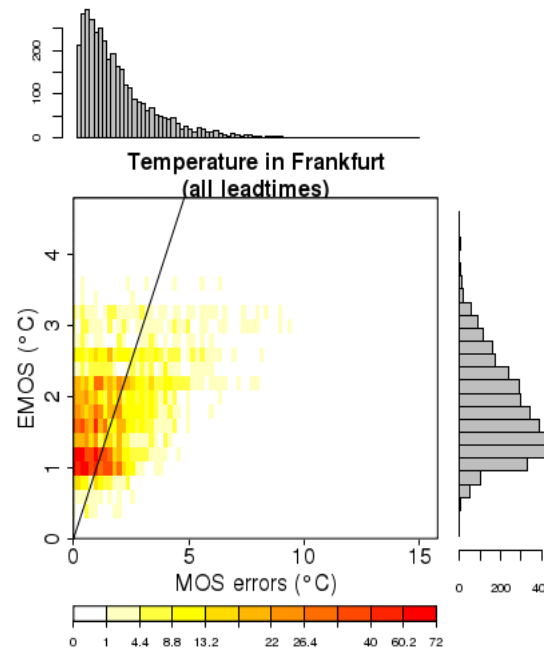
Ens. Mean: Errors of Ensemble Mean
 MOS: Errors of MOS
 EMOS: Estimated Errors of MOS

Estimated Errors are usually too small,
 but show weaker outliers

EnsembleMOS for ECMWF-EPS

■ Verification of 2013 – 2m temperature errors

Frankfurt

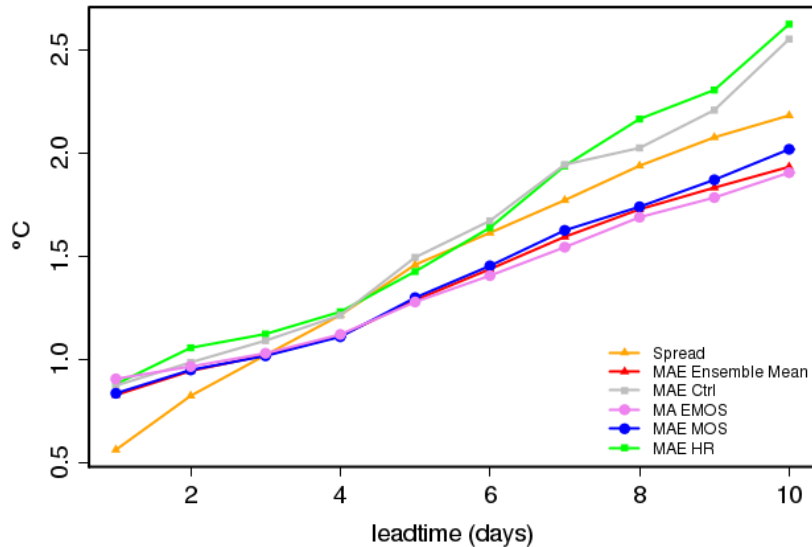


MOS: Errors of MOS
EMOS: Estimated Errors of MOS

EnsembleMOS for ECMWF-EPS

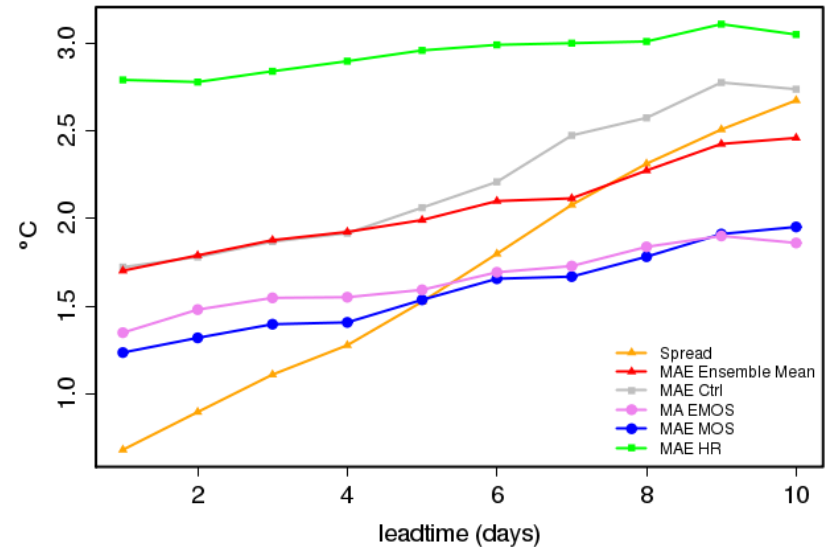
■ Verification of 2013 – 2m temperature errors

Comparison of Ensemble, MOS, High Res. and Control of Temperature in Dublin (20130102 - 20140110)



Dublin

Comparison of Ensemble, MOS, High Res. and Control of Temperature in Rabat (Morocco) (20130102 - 20140110)



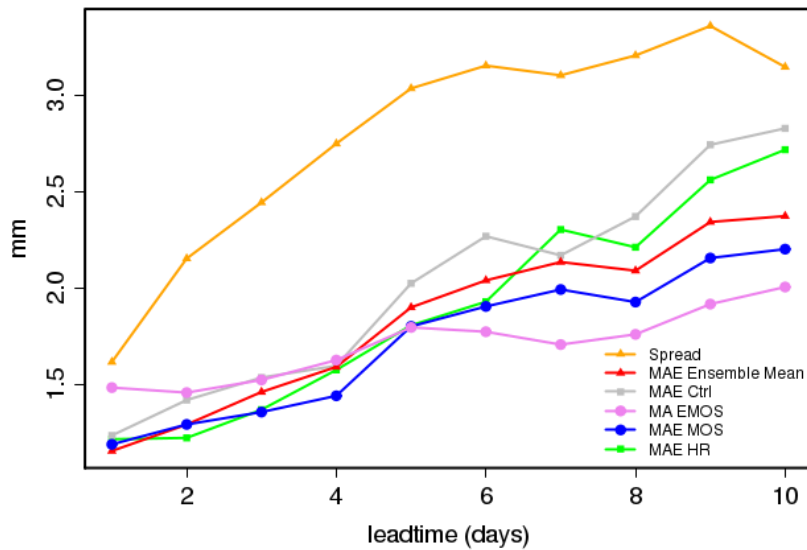
Rabat



EnsembleMOS for ECMWF-EPS

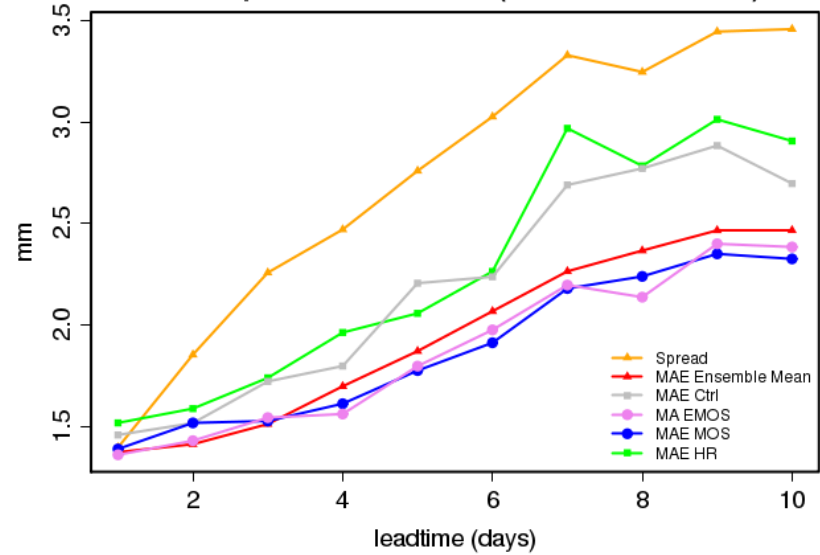
■ Verification of 2013 – 24h precipitation errors

Comparison of Ensemble, MOS, High Res. and Control of Precipitation 24h. in Frankfurt (20130102 - 20140110)



Frankfurt

Comparison of Ensemble, MOS, High Res. and Control of Precipitation 24h. in Dublin (20130102 - 20140110)



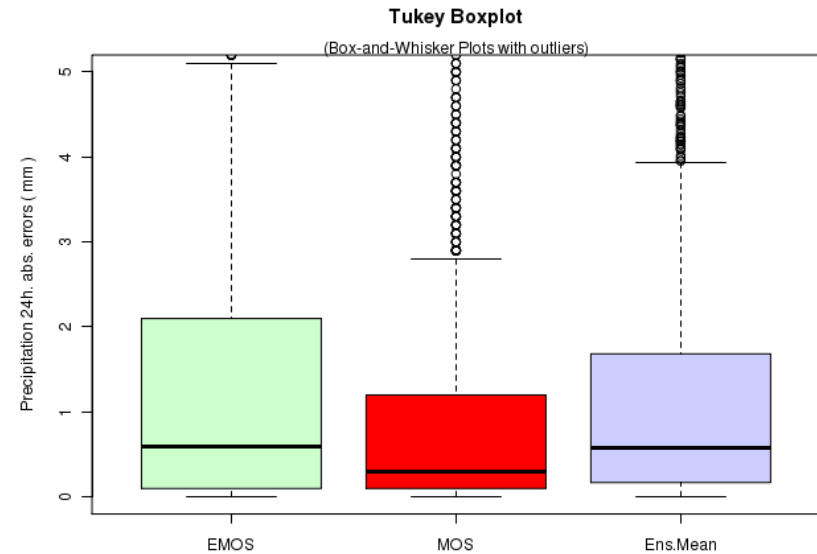
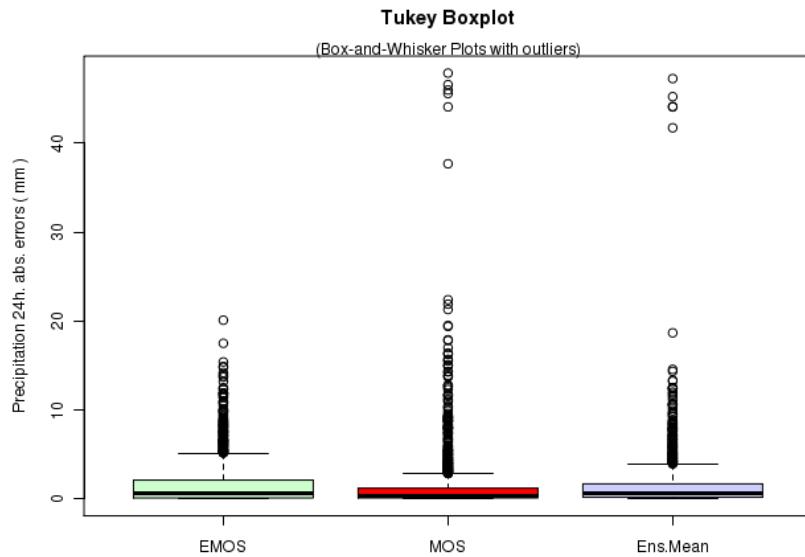
Dublin



EnsembleMOS for ECMWF-EPS

Frankfurt

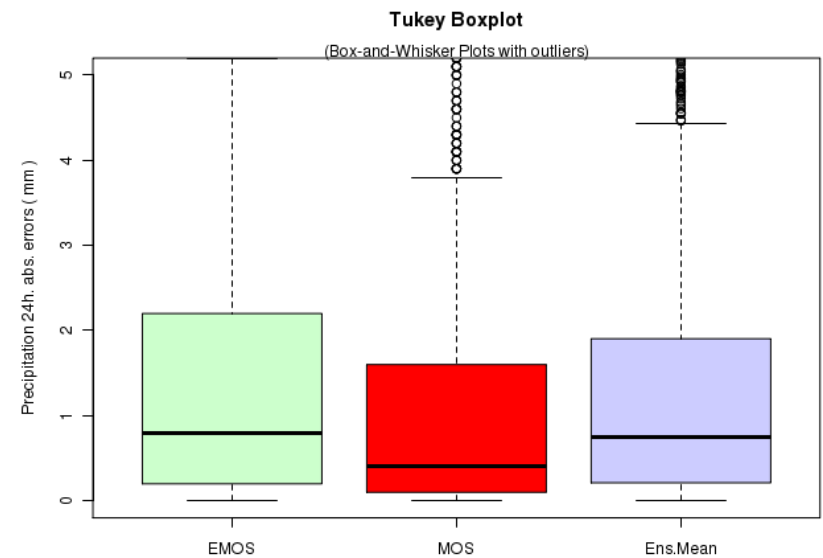
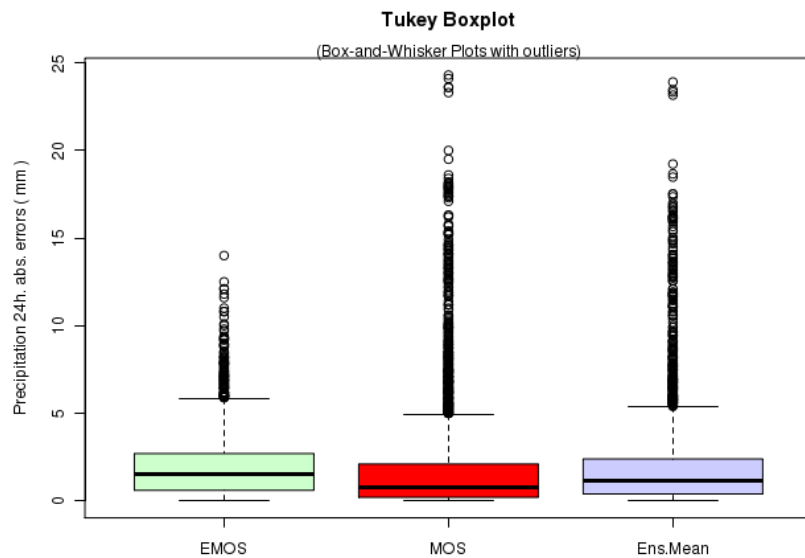
■ Verification of 2013 – 24h precipitation errors



EnsembleMOS for ECMWF-EPS

Dublin

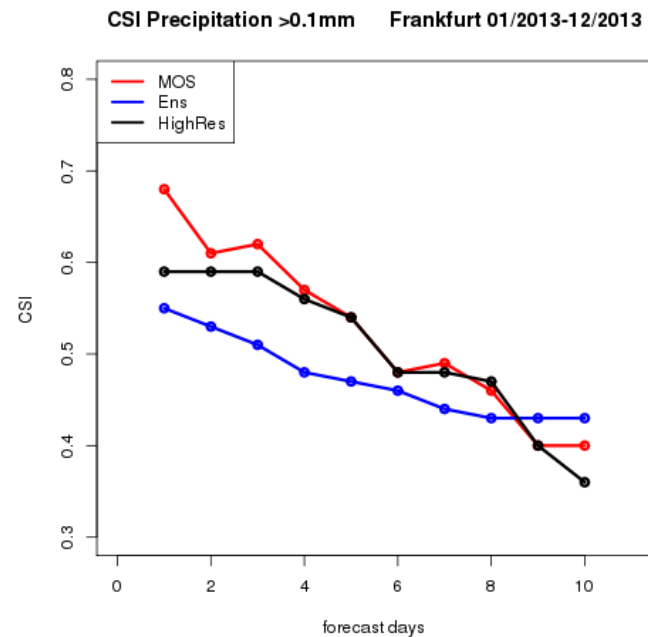
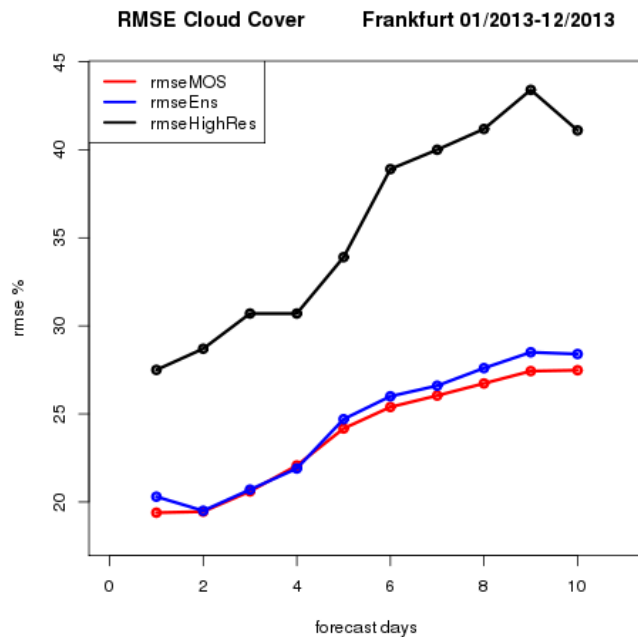
■ Verification of 2013 – 24h precipitation errors



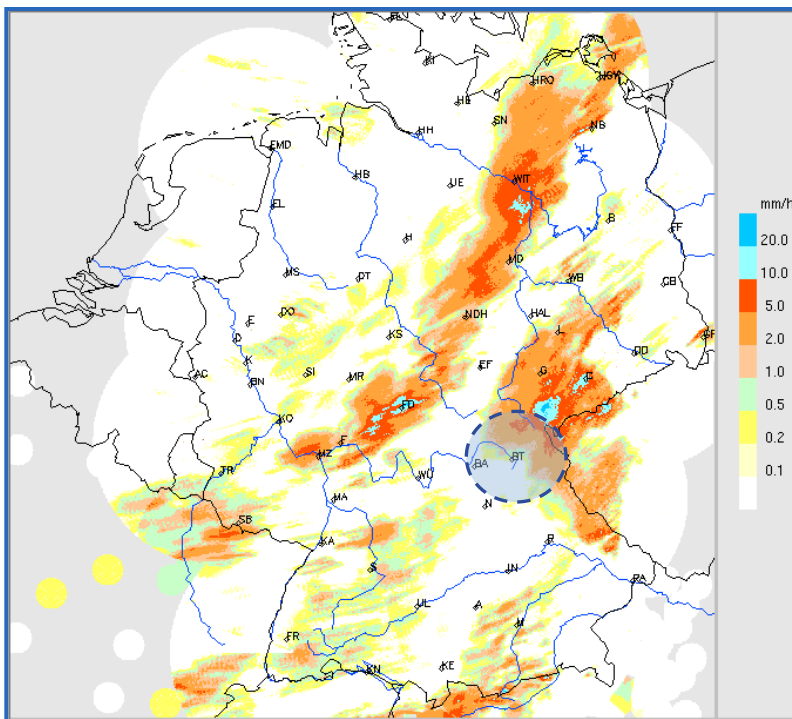
EnsembleMOS for ECMWF-EPS

Frankfurt

■ Verification of 2013 – cloud coverage and 24h precipitation (CSI, TS)



Gauge adjusted radar products as predictands (T. Hirsch)



■ Probabilities of Precipitation

- $P(RR > 15 \text{ mm/1h})$
- $P(RR > 40 \text{ mm/12h})$

■ standard: synoptic observations

■ idea: use **radar-data (RW, 1x1 km)**

- surrounding of stations ($r=8 \text{ km}$ und 40 km)
- relative frequencies of threshold exceedances in surrounding

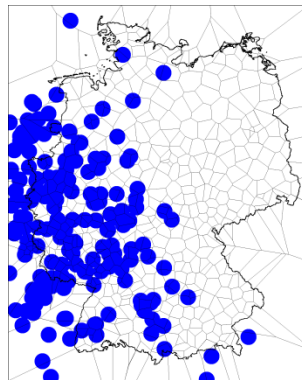
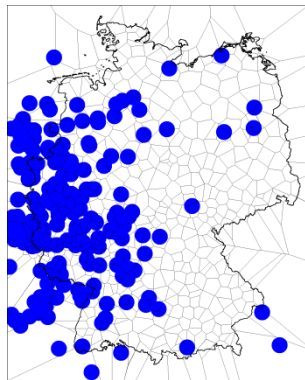
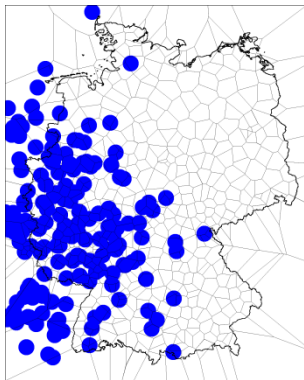
■ improved statistical sample

- higher representativity
- more extreme cases

1-hourly estimation of precipitation (gauge adjusted at stations)

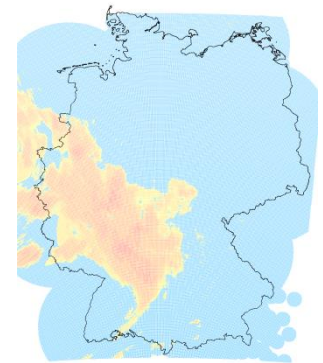
Area based probabilities

- Probability that an event occurs at least one time in any point of an area (for precipitation events currently)
- correct comparison between point observation (synop) and area mean (numerical model)
- derive area probabilities from point probabilities for arbitrary areas



3 of about 1000
Monte Carlo
Simulations

Radar
for validation



- **Idea:** place randomly circular precipitation cells so that the relative number of coverages match forecasted point probabilities at stations and count coverages for an arbitrary area.
- **Reference:** B. Krische, R. Hess, B. K. Reichert, V. Schmidt: "A probabilistic approach to the prediction of area weather events, applied to precipitation", Spatial Statistics, Elsevier, accepted 2015

Thank you for attention