

Calibration project at ECMWF

Stephan Hemri

CST group, Heidelberg Institute for Theoretical Studies

12 February 2015



Heidelberg Institute for
Theoretical Studies



- motivation for statistical post-processing
- post-processing design of the calibration project at ECMWF
- presentation of EMOS post-processing for T2M forecasts
- verification results for T2M and PPT24
- is there a temporal trend in the skill gap between raw ensemble and post-processed forecasts?

Why post-processing of ECMWF forecasts?

Global ensemble forecasting systems:

- are prone to probabilistic biases
- tend to underdispersion for surface variables

Post-processing methods:

- aim to remove probabilistic biases
- should maximize sharpness subject to calibration
- ensemble model output statistics (EMOS, Gneiting et al. (2005))
- Bayesian model averaging (BMA, Raftery et al. (2005))

Post-processing design

- ECMWF 12 UTC forecasts (1 HRES, 50 ENS, 1 CTRL)
- forecast lead times 1, . . . , 10 days
- variables: **T2M**, **PPT24**, V10, and TCC
- station-wise post-processing on global domain
- observation and forecast data from January 2002 to March 2014
- sliding window training periods
- used mainly EMOS because of its low computational cost

Let $\mathbf{f} = (f_1, f_2, \dots, f_K)^T$ be the vector of the K member raw ensemble forecasts (here: HRES, the mean of ENS, and CTRL):

- then the EMOS predictive density is

$$y|\mathbf{f} \sim g(m, \sigma),$$

where $g(\cdot)$ is a parametric density function with location and scale parameters m and σ .

- m and σ are functions of ensemble statistics.

EMOS for T2M

- For a training period $T = \{t_1, \dots, t_n\}$ we fit

$$y_{t_j} = c_0 + c_1 \sin\left(\frac{2\pi j}{365}\right) + c_2 \cos\left(\frac{2\pi j}{365}\right) + \varepsilon_{t_j}, \quad j = 1, \dots, n$$

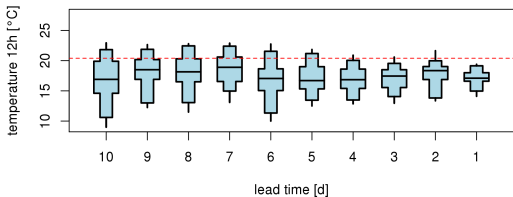
- with fitted value \tilde{y}_t as the climatological mean on day t
- $\tilde{f}_{\text{ENS},t}$, $\tilde{f}_{\text{CTRL},t}$, and $\tilde{f}_{\text{HRES},t}$ “climatological” forecast means
- With this:

$$m = \tilde{y} + a_1(f_{\text{HRES}} - \tilde{f}_{\text{HRES}}) + a_2(f_{\text{CTRL}} - \tilde{f}_{\text{CTRL}}) + a_3(f_{\text{ENS}} - \tilde{f}_{\text{ENS}})$$

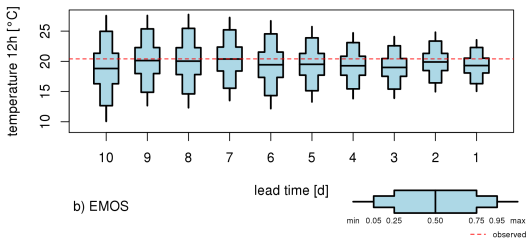
$$\sigma^2 = b_0 + b_1 s^2, \text{ where } s^2 \text{ is the ensemble variance}$$

Example: T2M forecasts for Vienna

EPSgrams: 20040505



a) raw ensemble



b) EMOS

Verification against observations:

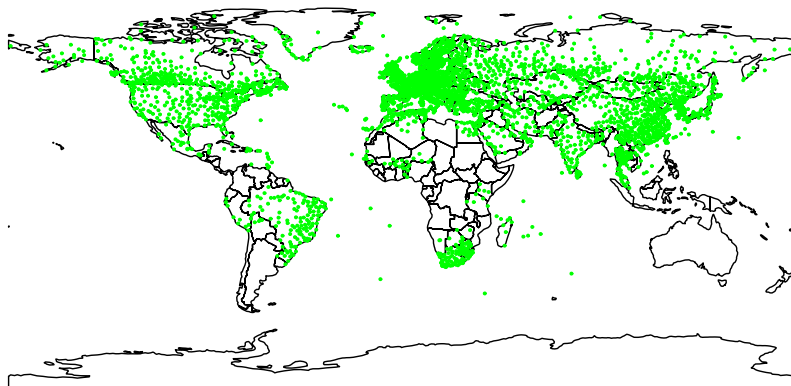
- continuous ranked probability score as main measure of skill:

$$\text{crps}(P, y) = \int_{-\infty}^{\infty} [P(x) - \mathbb{1}_{[x \geq y]}]^2 dx$$

- station-wise block bootstrapping to check for differences in the mean CRPS between raw ensemble and EMOS forecasts

Significant changes in CRPS for T2M

EMOS - raw ensemble, lead time: 3d



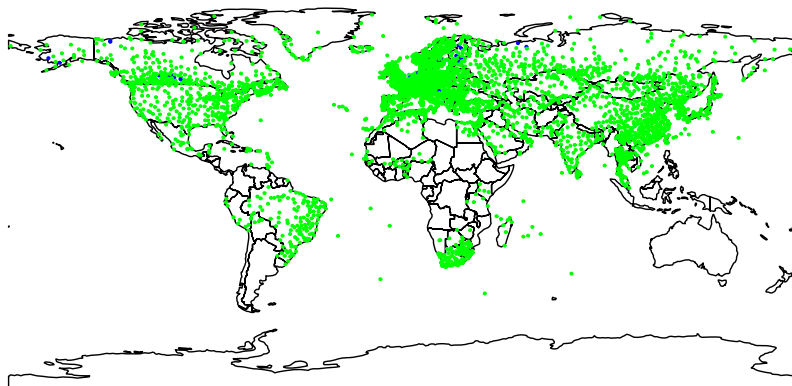
● improvement

● no significant change

● deterioration

Significant changes in CRPS for T2M

EMOS - raw ensemble, lead time: 6d



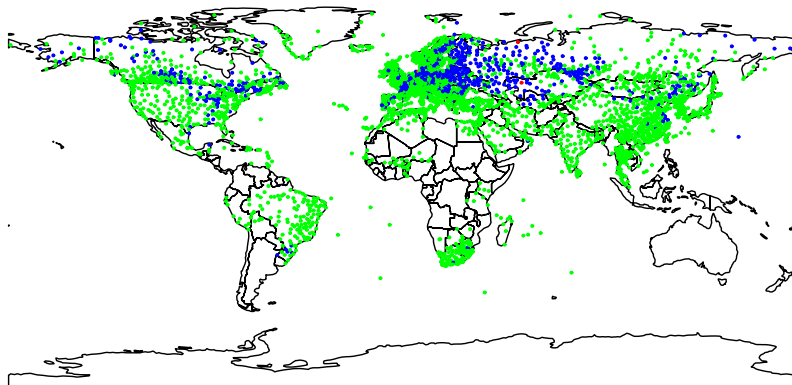
● improvement

● no significant change

● deterioration

Significant changes in CRPS for T2M

EMOS - raw ensemble, lead time: 10d



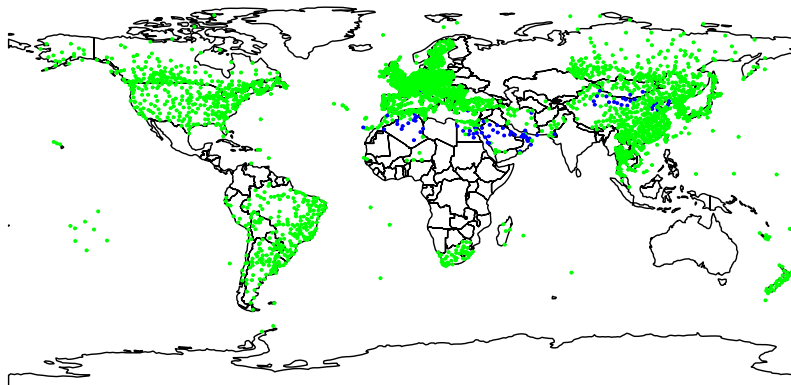
● improvement

● no significant change

● deterioration

Significant changes in CRPS for PPT24

EMOS - raw ensemble, lag 3d



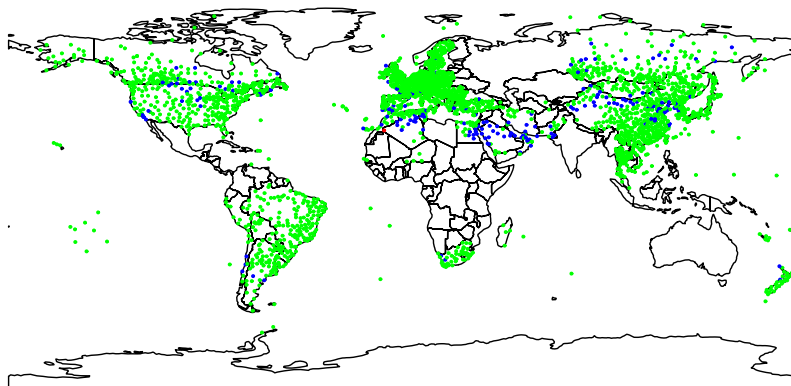
● improvement

● no significant change

● deterioration

Significant changes in CRPS for PPT24

EMOS - raw ensemble, lag 6d



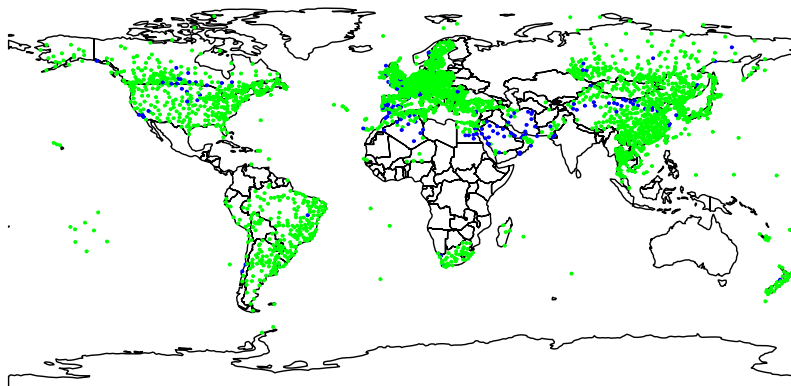
● improvement

● no significant change

● deterioration

Significant changes in CRPS for PPT24

EMOS - raw ensemble, lag 10d

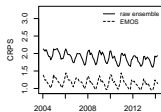


● improvement

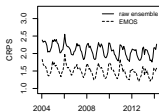
● no significant change

● deterioration

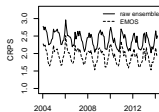
Global average CRPS



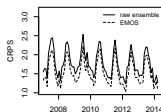
a) T2M: 3 d



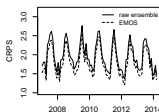
b) T2M: 6 d



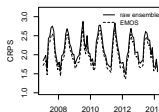
c) T2M: 10 d



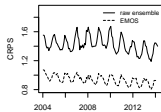
d) PPT24: 3 d



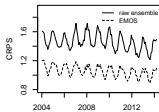
e) PPT24: 6 d



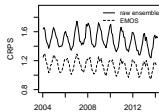
f) PPT24: 10 d



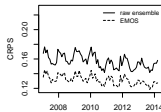
g) V10: 3 d



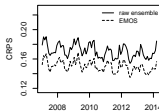
h) V10: 6 d



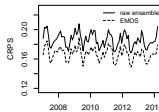
i) V10: 10 d



j) TCC: 3 d



k) TCC: 6 d



l) TCC: 10 d

But: skill of raw ensemble improves over time...

- ECMWF ensemble is under continuous development
- Hypothesis:
 - these improvements also reduce systematic errors, which can also be reduced by post-processing
 - hence, the gap in skill between raw ensemble and post-processed forecasts narrows over time
 - and post-processing might lose its justification

Evaluation of the evolution of ΔCRPS

- Monthly time series of CRPS differences:

$$\Delta\text{CRPS}_t = \text{CRPS}_{\text{raw},t} - \text{CRPS}_{\text{EMOS},t}$$

- Model 1 - parametric:

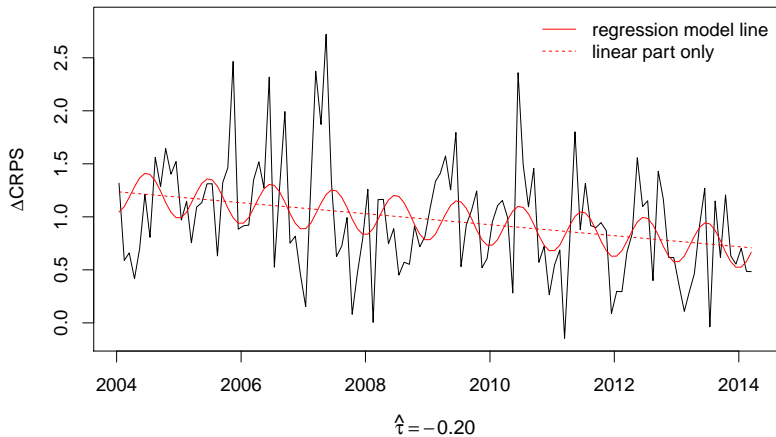
$$\Delta\text{CRPS}_t = \beta_0 + \beta_1 t + \beta_2 \sin\left(\frac{2\pi t}{12}\right) + \beta_3 \cos\left(\frac{2\pi t}{12}\right) + \epsilon, \quad \epsilon \sim \mathcal{N}(0, \sigma^2)$$

- Model 2 - Kendall's τ rank correlation coefficient for pairs (t, r_t) , where r_t are the residues of:

$$\Delta\text{CRPS}_t = \gamma_0 + \gamma_1 \sin\left(\frac{2\pi t}{12}\right) + \gamma_2 \cos\left(\frac{2\pi t}{12}\right) + \epsilon, \quad \epsilon \sim \mathcal{N}(0, \sigma^2)$$

Example station

Mukdahan, Thailand (16°32' N, 104°43' E)



Percentages of stations with significant trend in ΔCRPS^a

| | | | parametric model | | Kendall's τ statistics | |
|--------------------|------|----------------------|------------------|-------|-----------------------------|-------|
| | | | T2M | PPT24 | T2M | PPT24 |
| forecast lead time | 3 d | no significant trend | 42 % | 76 % | 44 % | 77 % |
| | | negative trend | 34 % | 19 % | 32 % | 18 % |
| | | positive trend | 24 % | 5 % | 24 % | 5 % |
| | 6 d | no significant trend | 46 % | 82 % | 48 % | 82 % |
| | | negative trend | 31 % | 14 % | 29 % | 13 % |
| | | positive trend | 23 % | 4 % | 23 % | 5 % |
| | 10 d | no significant trend | 54 % | 83 % | 54 % | 82 % |
| | | negative trend | 27 % | 11 % | 26 % | 11 % |
| | | positive trend | 19 % | 6 % | 20 % | 7 % |

^aPercentages of stations (totals are 4160 (T2M) and 2917 (PPT24)) showing no, negative, or positive trend in monthly ΔCRPS values against time at a significance level of 0.05

Conclusions

- univariate post-processing using EMOS improves skill at almost any station and lead time for the variables T2M, PPT24, V10, and TCC
- probabilistic skill of both raw ensemble and EMOS forecasts improves over time
- gap in skill (Δ CRPS) remains almost constant over time
 - improvements to the atmospheric model increase potential skill
 - statistical post-processing will keep adding skill in the foreseeable future

References

- [1] Gneiting, T., and A. E. Raftery, 2007: Strictly proper scoring rules, prediction, and estimation. *J. Am. Stat. Assoc.* **102**, 359–378.
- [2] Gneiting, T., A. E. Raftery, A. H. Westveld, and T. Goldman, 2005: Calibrated probabilistic forecasting using ensemble model output statistics and minimum CRPS estimation. *Mon. Weather Rev.* **133** (5), 1098-1118.
- [3] Hemri, S., M. Scheuerer, F. Pappenberger, K. Bogner, and T. Haiden, 2014: Trends in the predictive performance of raw ensemble weather forecasts. *Geophys. Res. Lett.* **41**, 9197-9205.
- [4] Raftery, A. E., T. Gneiting, F. Balabdaoui, and M. Polakowski, 2005: Using Bayesian model averaging to calibrate forecast ensembles. *Mon. Weather Rev.* **133** (2), 1155-1174.
- [5] M. Scheuerer, 2014: Probabilistic quantitative precipitation forecasting using ensemble model output statistics. *Q. J. R. Meteorol. Soc.* **140**(680), 1086-1096.
- [6] Scheuerer M., and L. Büermann, 2014: Probabilistic quantitative precipitation forecasting using ensemble model output statistics. *J. R. Stat. Soc. Ser. C* **63**(3), 405-422.
- [7] Thorarinsdottir, T. L., and T. Gneiting, 2010: Probabilistic forecasts of wind speed: Ensemble model output statistics using heteroscedastic censored regression. *J. R. Stat. Soc. Ser. A* **173**, 371-388.